

```

1 MACHINE
2   WaterTank_1Ctrl_2Tanks_Cylinder
3   REFINES
4     WaterTank_ode
5   SEES
6     WaterTank_2Tanks_Cylinder_Ctx
7   VARIABLES t, x_s, h1, h2
8   INVARIANTS
9     inv1: h1 ∈ RRealPlus → RReal
10    inv2: h2 ∈ RRealPlus → RReal
11    inv3: V = LinComb2(B1, h1, B2, h2)
12 EVENTS
13   INITIALISATION
14   WITH
15     V': V' = LinComb2(B1, h1', B2, h2')
16   THEN
17     act1: t := Rzero
18     act2:
19       h1, h2 :|
20         h1' ∈ RRealPlus → S ∧
21         h2' ∈ RRealPlus → S ∧
22         solutionOf(
23           RRealPlus,
24           h1',
25           ode(
26             NoFlow,
27             H10,
28             Rzero
29           )
30         ) ∧
31         solutionOf(
32           RRealPlus,
33           h2',
34           ode(
35             NoFlow,
36             H20,
37             Rzero
38           )
39         )
40     act3: x_s := Stable
41 END
42
43 Progress
44 REFINES Progress
45 THEN
46   act1: t :| t' ∈ RRealPlus ∧ (t ↦ t' ∈ lt)
47 END
48
49 Behave
50 REFINES Behave
51 ANY e
52 WHERE
53   grd1: e ∈ DE(S)
54   grd2: Solvable(Closed2Infinity(t), e)
55 WITH
56   V': V' = LinComb2(B1, h1', B2, h2')
57 THEN
58   act1:
59     h1, h2 :|
60       h1' ∈ RRealPlus → S ∧
61       h2' ∈ RRealPlus → S ∧
62       AppendSolutionBAP(
63         e,
64         RRealPlus, Closed2Open(Rzero, t), Closed2Infinity(t),
65         LinComb2(B1, h1, B2, h2),
66         LinComb2(B1, h1', B2, h2')
67       )
68 END
69
70 ctrl_sense_too_high
71 REFINES ctrl_sense_too_high
72 WHERE
73   grd1: Vhigh ↦ LinComb2(B1, h1, B2, h2)(t) ∈ leq

```

```

74 THEN
75   act1:  $x\_s := Emptying$ 
76 END
77
78 ctrl_sense_too_low
79 REFINES  $ctrl\_sense\_too\_low$ 
80 WHERE
81   grd1:  $LinComb2(B1, h1, B2, h2)(t) \mapsto Vlow \in leq$ 
82 THEN
83   act1:  $x\_s := Filling$ 
84 END
85
86 ctrl_transition_emptying
87 REFINES  $ctrl\_transition\_emptying$ 
88 WHERE
89   grd1:  $Vlow \mapsto LinComb2(B1, h1, B2, h2)(t) \in lt$ 
90 THEN
91   act1:  $x\_s := Emptying$ 
92 END
93
94 ctrl_transition_filling
95 REFINES  $ctrl\_transition\_filling$ 
96 WHERE
97   grd1:  $LinComb2(B1, h1, B2, h2)(t) \mapsto Vhigh \in lt$ 
98 THEN
99   act1:  $x\_s := Filling$ 
100 END
101
102 ctrl_transition_normal
103 REFINES  $ctrl\_transition\_normal$ 
104 WHERE
105   grd1:  $Vlow \mapsto LinComb2(B1, h1, B2, h2)(t) \in lt$ 
106   grd2:  $LinComb2(B1, h1, B2, h2)(t) \mapsto Vhigh \in lt$ 
107 THEN
108   act1:  $x\_s := Normal$ 
109 END
110
111 ctrl_transition_stable
112 REFINES  $ctrl\_transition\_stable$ 
113 WHERE
114   grd1:  $Vlow \mapsto LinComb2(B1, h1, B2, h2)(t) \in lt$ 
115   grd2:  $LinComb2(B1, h1, B2, h2)(t) \mapsto Vhigh \in lt$ 
116 THEN
117   act1:  $x\_s := Stable$ 
118 END
119
120 ctrl_actuate_pumps
121 REFINES  $ctrl\_actuate\_pumps$ 
122 ANY io, ss
123 WHERE
124   grd4: ss  $\in STATES$ 
125   grd5:  $x\_s = ss$ 
126   grd6:  $io \in SingleTankPolicy(x\_s)$ 
127 WITH
128    $V' := LinComb2(B1, h1', B2, h2')$ 
129    $\Phi :=$ 
130      $\Phi \in RRealPlus \times S \rightarrow S \wedge$ 
131      $isFlowODE(Emptying, Closed2Infinity(t), \Phi, Rzero, Vmax) \wedge$ 
132      $Solvable(Closed2Infinity(t), ode(\Phi, V(t), t)) \wedge$ 
133      $(\forall h1\_ h2\_ .$ 
134        $h1\_ \in Closed2Infinity(t) \rightarrow RReal \wedge h2\_ \in Closed2Infinity(t) \rightarrow RReal \wedge$ 
135        $solutionOf(Closed2Infinity(t), h1\_, FlowIOODE(Rzero, H1max, delta\_in\_h1, delta\_out\_h1)(io)(t \mapsto h1(t))) \wedge$ 
136        $solutionOf(Closed2Infinity(t), h2\_, FlowIOODE(Rzero, H2max, delta\_in\_h2, delta\_out\_h2)(io)(t \mapsto h2(t))) \Rightarrow$ 
137        $solutionOf(Closed2Infinity(t), LinComb2(B1, h1\_, B2, h2\_), ode(\Phi, V(t), t))$ 
138   )
139 THEN
140   act1:
141      $h1, h2 : |$ 
142      $h1' \in RRealPlus \rightarrow S \wedge$ 
143      $h2' \in RRealPlus \rightarrow S \wedge$ 
144      $AppendSolutionBAP($ 
145        $FlowIOODE(Rzero, H1max, delta\_in\_h1, delta\_out\_h1)(io)(t \mapsto h1(t)),$ 
146        $RRealPlus,$ 
147        $Closed2Open(Rzero, t), Closed2Infinity(t),$ 

```

```
148       $h1, h1'$ 
149      )^
150      AppendSolutionBAP(
151          FlowIOODE(Rzero, H2max, delta_in_h2, delta_out_h2)(io)(t  $\mapsto$  h2(t)),
152          RRealPlus,
153          Closed2Open(Rzero, t), Closed2Infinity(t),
154          h2, h2'
155      )
156  END
157
158  END
```