

Knowledge and action: how should we combine their logics?

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FroCoS 2015, Wroclaw, September 2015

Outline

- ① Motivation: simple logics of action and knowledge needed
- ② Adding higher-order observability information
- ③ Application: the gossip problem
- ④ Adding public announcements
- ⑤ Application: the muddy children puzzle
- ⑥ Application: boolean games

Logics of knowledge and action

- fruitful in CS since 30+ years
 - epistemic temporal logics
[Halpern et col., Lomuscio, . . . , ≥ 1990]
 - epistemic extension of the situation calculus
[Scherl & Levesque, . . . , ≥ 1995]
 - Dynamic Epistemic Logics DEL
[van Benthem, Moss, Baltag, van Ditmarsch, . . . , ≥ 2000]
- typically multi-dimensional modal logics
 - high complexity; often undecidable
- simplest combined logic of knowledge and action?
 - a typical question of philosophical logic
 - also relevant for computer science

Logics of knowledge and action

- idea [v.d.Hoek & Wooldridge, inspired from model checkers]:
 - ground action on propositional control
 - ground knowledge on propositional observability

- logics:

ECL-PO = “Epistemic Coalition Logic of Propositional Control with Partial Observability” [vdHTW11]

LRC = “Logic of Revelation and Concealment” [vdHIW12]

- this talk:
 - reduce to *Dynamic Logic of Propositional Assignments* DL-PA
 - overcome some limitations of the original approach

Grounding action on propositional control

agent i controls propositional variable p or not

- define accessibility relation for group of agents $J \subseteq \text{Agt}$:

$$R_J = \{(v, v') : v(p) = v'(p) \text{ if } p \in \text{PVar} \text{ not controlled by any } i \in J\}$$

- coalitional effectivity *ceteris paribus*:

$$vR_Jv' \quad \text{iff} \quad \text{at } v, \text{ if the other agents don't act then } J \text{ can guarantee that the next state of the world is } v'$$

- interpret operator of coalitional effectivity:

$$v \models \diamond_J \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v' \text{ such that } vR_Jv'$$

\implies Coalition Logic of Propositional Control

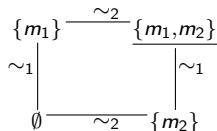
- approximates ATL/Pauly's operator of coalitional effectivity:

$$\langle\langle \{i\} \rangle\rangle X \varphi \approx \diamond_{\{i\}} \square_{\text{Agt} \setminus \{i\}} \varphi$$

Grounding knowledge on propositional observability

agent i observes whether propositional variable p is true or not

- muddy children: child 1 sees whether child 2 is muddy; doesn't see whether 1 is muddy
- define indistinguishability relation:



$$\sim_i = \{(v, v') : v(p) = v'(p) \text{ for every } p \in PVar \text{ observed by } i\}$$

\implies equivalence relation on the set of all valuations

- interpret epistemic operator as usual:

$$v \models K_i \varphi \text{ iff } v' \models \varphi \text{ for every } v' \text{ such that } v \sim_i v'$$

- pushes the envelope of the 'DEL philosophy' of replacing accessibility relations by model updates

(while DELs still have accessibility relations for knowledge)

Propositional observability: properties

+ all axiom schemas of S5 valid

– observability is common knowledge:

$$\begin{aligned} (K_i p \vee K_i \neg p) &\rightarrow K_j (K_i p \vee K_i \neg p) \\ \neg(K_i p \vee K_i \neg p) &\rightarrow K_j \neg(K_i p \vee K_i \neg p) \end{aligned}$$

– distributes over disjunction:

$$K_i (p \vee q) \leftrightarrow (K_i p \vee K_i q)$$

so:

- initial situation of the muddy children puzzle can be modelled
- ... but not the situation after the father's announcement "one of you is muddy"!

– related:

- logic only accounts for observation but not for *communication*

Embedding into DL-PA

- can be captured in

Dynamic Logic of Propositional Assignments DL-PA

1. introduce new propositional variables

$C_i p$ = “ i controls p ”

$S_i p$ = “ i sees p ”

2. identify \Diamond_i and K_i with **assignment programs**:

for φ boolean with $PVar(\varphi) = \{p_1, \dots, p_n\}$,

$$\begin{aligned} \Diamond_i \varphi \leftrightarrow & \langle (\neg C_i p_1? \sqcup (C_i p_1?; (+p_1 \sqcup -p_1))) ; \\ & \dots ; \\ & (\neg C_i p_n? \sqcup (C_i p_n?; (+p_n \sqcup -p_n))) \rangle \varphi \end{aligned}$$

$$\begin{aligned} K_i \varphi \leftrightarrow & [(S_i p_1? \sqcup (\neg S_i p_1?; (+p_1 \sqcup -p_1))) ; \\ & \dots ; \\ & (S_i p_n? \sqcup (\neg S_i p_n?; (+p_n \sqcup -p_n)))] \varphi \end{aligned}$$

\implies start with innermost modal operators!

3. axiomatize exclusive and exhaustive control

$$\left(\bigwedge \neg(C_i p \wedge C_j p) \right) \wedge \left(\bigvee C_i p \right)$$

DL-PA

- assignment programs built by the PDL program operators from

$+p$ = “make p true”

$-p$ = “make p false”

- generalizes QBF:

$$\forall p. \varphi \leftrightarrow [+p \sqcup -p]\varphi$$

- compact models
 - valuations of classical propositional logic
- PSPACE complete (both model checking and SAT)
- uniform substitution does not preserve validity

Adding higher-order observability information

Higher-order observability

- idea: introduce **higher-order visibility atoms**

$S_i p$ = “ i sees the value of p ”

$S_i S_j p$ = “ i sees whether j sees the value of p ”

$S_i S_j S_k p$ = “...”

- general schema as before:

$$K_i \varphi \leftrightarrow [\pi_{i, \text{Atm}(\varphi)}] \varphi$$

where $\pi_{i, \text{Atm}(\varphi)} = (S_i \alpha_1? \sqcup (\neg S_i \alpha_1?; (+\alpha_1 \sqcup -\alpha_1))) ; \dots$

examples:

$$K_i p \leftrightarrow p \wedge S_i p$$

$$K_i \neg p \leftrightarrow \neg p \wedge S_i p$$

$$K_i K_j p \leftrightarrow K_i (p \wedge S_j p)$$

$$\leftrightarrow K_i p \wedge K_i S_j p$$

$$\leftrightarrow p \wedge S_i p \wedge S_j p \wedge S_i S_j p$$

DEL-PA0 = DEL of Propositional Assignment and Observation

Language of DEL-PAO

- visibility atoms:

$$\alpha ::= p \mid S_i \alpha \mid JS \alpha$$

with p propositional variable and i agent

$$\begin{aligned} p &= \dots \\ S_i \alpha &= \dots \\ JS \alpha &= \text{“all agents } \textit{jointly} \textit{ see whether } \alpha \text{”} \end{aligned}$$

- formulas and programs as in PDL:

$$\begin{aligned} \varphi &::= \alpha \mid \neg \varphi \mid \varphi \wedge \varphi \mid K_i \varphi \mid CK \varphi \mid [\pi] \varphi \\ \pi &::= +\alpha \mid -\alpha \mid \pi; \pi \mid \pi \sqcup \pi \mid \varphi? \end{aligned}$$

with i agent and α visibility atom

DEL-PAO: valuations

- valuation = sets of visibility atoms v
- define indistinguishability relations:
 - $v \sim_i v'$ iff $\forall \alpha$, if $S_i \alpha \in v$ then $v(\alpha) = v'(\alpha)$
 - $v \sim_{Agt} v'$ iff $\forall \alpha$, if $JS \alpha \in v$ then $v(\alpha) = v'(\alpha)$
- problem: are reflexive, but neither transitive nor symmetric
 - $\emptyset \sim_i v$ for every v
 - $v \not\sim_i \emptyset$ as soon as $p \in v$ and $S_i p \in v$

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- solution: valuations must be **introspective**

DEL-PAO: introspective valuations

Definition

v is **introspective** iff

1. $S_i S_i \alpha \in v$
2. $JS JS \alpha \in v$
3. $JS S_i S_i \alpha \in v$
4. if $JS \alpha \in v$ then $S_i \alpha \in v$
5. if $JS \alpha \in v$ then $JS S_i \alpha \in v$

Theorem

*introspective valuations contain all atoms of form “ $\dots S_i S_i \dots p$ ”
and “ $\dots JS JS \dots p$ ”*

Theorem

\sim_i and \sim_{Agt} are equivalence relations on introspective valuations

DEL-PA0: interpretation of formulas

- interpretation of formulas:

$$v \models \alpha \quad \text{iff} \quad \alpha \in v$$

$$v \models K_i \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v \sim_i v'$$

$$v \models CK \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v \sim_{Agt} v'$$

$$v \models [\pi] \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v R_\pi v'$$

- interpretation of programs:

$$v R_{+\alpha} v' \quad \text{iff} \quad v' = v \cup \{\alpha \text{ and its introspective consequences}\}$$

$$v R_{-\alpha} v' \quad \text{iff} \quad \alpha \text{ is not an introspectively valid atom} \\ \text{and } v' = v \setminus \{\alpha \text{ and its causes}\}$$

$$v R_{\pi_1; \pi_2} v' \quad \text{iff} \quad \text{there is } v'' \text{ such that } v R_{\pi_1} v'' R_{\pi_2} v'$$

$$v R_{\pi_1 \sqcup \pi_2} v' \quad \text{iff} \quad v R_{\pi_1} v' \text{ or } v R_{\pi_2} v'$$

$$v R_{\varphi?} v' \quad \text{iff} \quad v = v' \text{ and } v \models \varphi$$

Valid in introspective valuations

- S5 axiom schemas valid for K_i :

$$K_i \varphi \rightarrow \varphi$$

$$K_i \varphi \rightarrow K_i K_i \varphi$$

$$\neg K_i \varphi \rightarrow K_i \neg K_i \varphi$$

- fixed-point axiom schema valid for CK :

$$CK \varphi \leftrightarrow \varphi \wedge \bigwedge_i K_i CK \varphi$$

- induction axiom schema **invalid** for CK :

$$\varphi \wedge CK (\varphi \rightarrow \bigwedge_i K_i CK \varphi) \not\vdash CK \varphi$$

Properties of DEL-PA0, ctd.

- sound and complete axiomatization

1. reduction axioms for K_i , CK , $[\pi]$

$$K_i \varphi \leftrightarrow [\pi_{i, ATM(\varphi)}] \varphi$$

$$CK \varphi \leftrightarrow [\pi_{Agt, ATM(\varphi)}] \varphi$$

$$[\pi \sqcup \pi'] \varphi \leftrightarrow \dots$$

...

$$[+\alpha] \varphi \leftrightarrow \dots$$

$$[-\alpha] \varphi \leftrightarrow \dots$$

2. introspection axioms:

$$S_i S_i \alpha$$

$$JS JS \alpha$$

$$JS S_i S_i \alpha$$

$$JS \alpha \rightarrow S_i \alpha$$

$$JS \alpha \rightarrow JS S_i \alpha$$

3. modus ponens

4. rules of equivalence for K_i , CK , $[\pi]$

Properties of DEL-PA0, ctd.

- complexity: SAT and MC both PSPACE-complete
 1. MC can be polynomially reduced to SAT
 2. SAT can be polynomially reduced to MC
 3. lower bound for MC: polynomial encoding of QBF

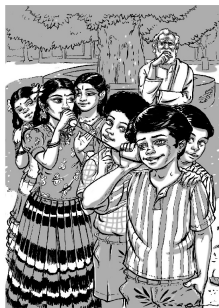
$$v \models \forall p. \varphi \text{ iff } v \models [+p \sqcup -p]\varphi$$
 4. upper bound for MC: polynomial encoding into Dynamic Logic of Propositional Assignments DL-PA [HLTM11, BHT13]
- \implies better than SAT for $S5_n^{CK}$ (EXPTIME-complete)

Application: the gossip problem

The gossip problem

[Baker&Shostak, Discrete Mathematics 1972]

- six friends each with a secret σ_i
- they can call each other to exchange every secret they know
- how many calls to spread all secrets among all friends?



(picture from [vDK15])

The gossip problem

- goal: shared knowledge

$$\mathbf{EK} \varphi = \bigwedge_{i \in \mathit{Agt}} K_i \varphi$$

(‘everybody knows’)

- optimal algorithm: 8 calls to obtain $\mathbf{EK}(\sigma_1 \wedge \dots \wedge \sigma_6)$
 - for n agents: $2(n-1)$ calls
- versatile:
 - reasoning about social networks, disease spreading, ...
 \implies take some network structure into account
 - different kinds of protocols
 \implies distributed vs. centralized
- hot topic in the DEL community:
 - [AvDGvdH14, vDK15]
 - ongoing work by v.Ditmarsch, v.Eijck, v.d.Hoek, Grossi, Apt
- multiagent planning’s blocksworld?

The gossip problem in DEL-PAO

call = program:

$$\text{call}_{ij} = ((K_i \sigma_1?; +S_j \sigma_1) \sqcup \neg K_i \sigma_1?); \cdots ; ((K_i \sigma_6?; +S_j \sigma_6) \sqcup \neg K_i \sigma_6?); \\ ((K_j \sigma_1?; +S_i \sigma_1) \sqcup \neg K_j \sigma_1?); \cdots ; ((K_j \sigma_6?; +S_i \sigma_6) \sqcup \neg K_j \sigma_6?)$$

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For valuation v such that $\sigma_i \in v$ and such that $S_i \sigma_j \in v$ iff $i=j$:

$$v \models [call_{12}; call_{34}; call_{56}; call_{13}; call_{45}; call_{16}; call_{24}; call_{35}] \text{ EK } \left(\bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

$$v \models \langle \left(\bigcup_{1 \leq i, j \leq 6} \neg S_i \sigma_j?; call_{ij} \right) \rangle^6 \text{ EK } \left(\bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

$$v \models \left[\left(\bigcup_{1 \leq i, j \leq 6} \neg S_i \sigma_j?; call_{ij} \right) \right]^5 \neg \text{ EK } \left(\bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

The gossip problem: attaining higher-order shared knowledge

- attain shared knowledge of level 2:

$$EK EK \left(\bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

- attain shared knowledge of level k :

$$EK^k \left(\bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

- algorithm with $(k+1) \times (n-1)$ calls to attain shared knowledge of order 2 [Herzig & Maffre, submitted]
 - optimal?

Adding public announcements

Semantics: add current info state

[Herzig et al., ongoing]

- idea: evaluate epistemic formulas not only wrt agents' observations, but also wrt the current information state [CS15]
 - current information state = set of valuations W
 - pointed model = information state W + valuation v
- language: add public announcements
- truth conditions:

$$W, v \models [\psi!] \varphi \quad \text{iff} \quad W, v \models \psi \text{ implies } \|\psi\|_W, v \models \varphi$$

$$W, v \models K_i \varphi \quad \text{iff} \quad W, v' \models \varphi \text{ for every } v' \in W \text{ s.th. } v \sim_i v'$$
- properties:
 - reduction axioms \implies decidable
 - PSPACE complete

Application: the muddy children puzzle

Application: the muddy children puzzle

for v such that $S_i m_j \in v$ iff $i \neq j$ and $JS S_i m_j \in v$ for all i, j :

- ignorance persists for $n-2$ rounds

$$v \models \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) !] \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !] \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-2} \text{Ignorance}$$

- shared and even common knowledge comes after $n-1$ rounds

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-1} \text{EK} \bigwedge_i m_i$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-1} \text{CK} \bigwedge_i m_i$$

$$\text{with } \text{Ignorance} = \bigwedge_i (\neg K_i m_i \wedge \neg K_i \neg m_i)$$

Application: boolean games

Putting things together: accounting for epistemic boolean games

- boolean games
 - exclusive and exhaustive propositional control:

$$\left(\bigwedge_{i \neq j} \neg(C_i p \wedge C_j p) \right) \wedge \left(\bigvee_{i \in \text{Agt}} C_i p \right)$$

- strategy of agent i = truth values of i 's variables
 \implies strategy profile = valuation
- goal of agent i = propositional formula γ_i
 \implies utility of strategy profile v is 1 if $v \models \gamma_i$; is 0 otherwise
- strategy profile v is a Nash equilibrium iff

$$v \models \bigwedge_{i \in \text{Agt}} (\diamond_i \gamma_i \rightarrow \gamma_i)$$

Putting things together: accounting for epistemic boolean games

- epistemic boolean games:
 - generalize propositional variables to atoms: $S_i C_j p, \dots$
 - generalize goals to epistemic formulas
 - same definitions: strategy, Nash equilibrium, ...

example:

- agent 1 has a secret, s_1 , and 2 has a secret, s_2
- agent i may privately communicate his secret to j : $+S_j s_i$
- both have goal of 'fair division of information':

$$\gamma_1 = \gamma_2 = K_1 s_2 \leftrightarrow K_2 s_1$$

example:

- ... and agent 3 shouldn't learn anything:

$$\gamma_1 = \gamma_2 = (K_1 s_2 \leftrightarrow K_2 s_1) \wedge \neg K_3 s_1 \wedge \neg K_3 \neg s_1 \wedge \neg K_3 s_2 \wedge \neg K_3 \neg s_2$$

Conclusion and future work

- DEL-PAO = dynamic epistemic logic based on visibility
 - higher-order observations
 - no common knowledge of who sees what
- add public announcements
 - information state
- add propositional control: DEL-PAOC
- interesting complexity
- future work:
 - ?? from knowledge to belief
 - problem: guarantee introspection



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