

Knowledge Based Situation Discovery for Avionics Maintenance

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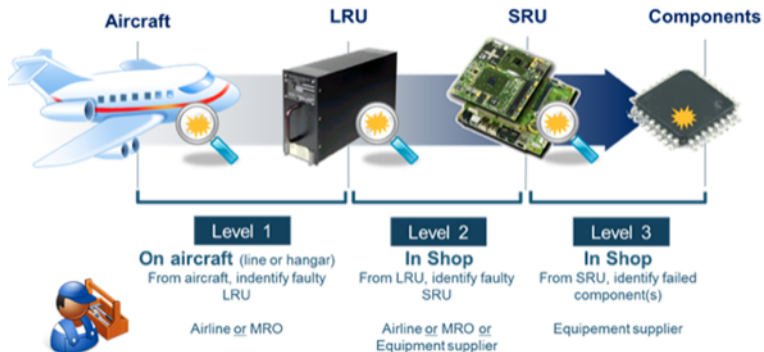
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- 4 Evaluation
- 5 Conclusions and Further Work

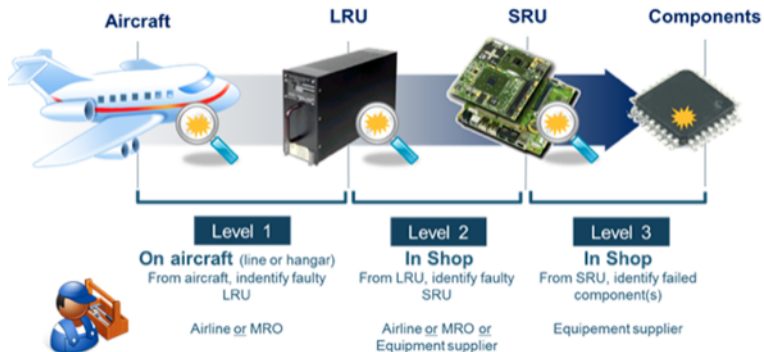
Context

LRU: Line Replacement Unit
 SRU: Shop Replacement Unit

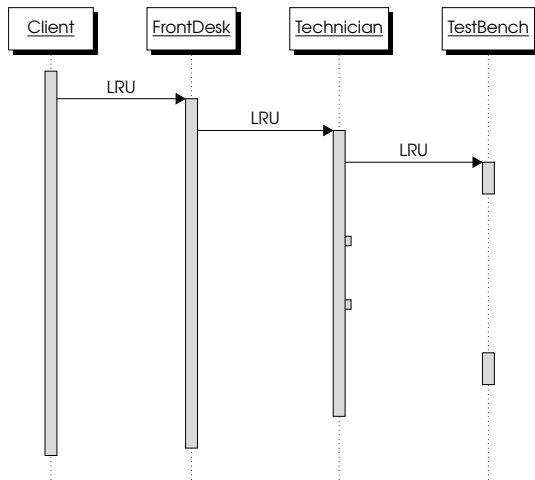


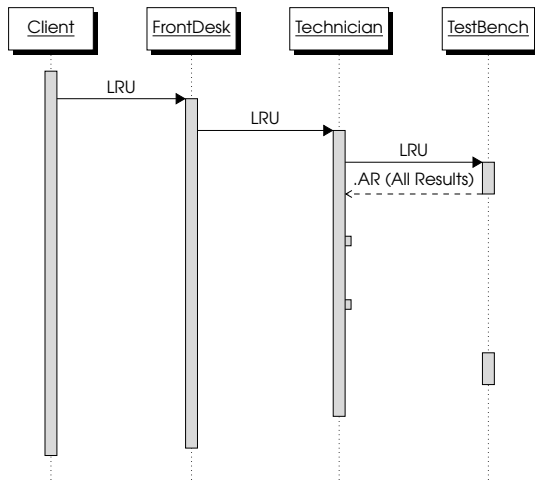
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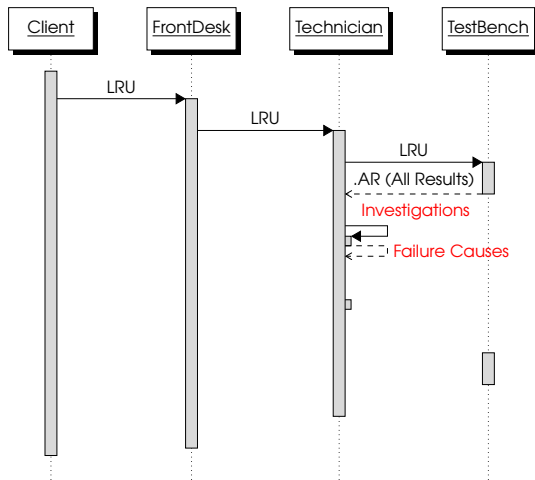
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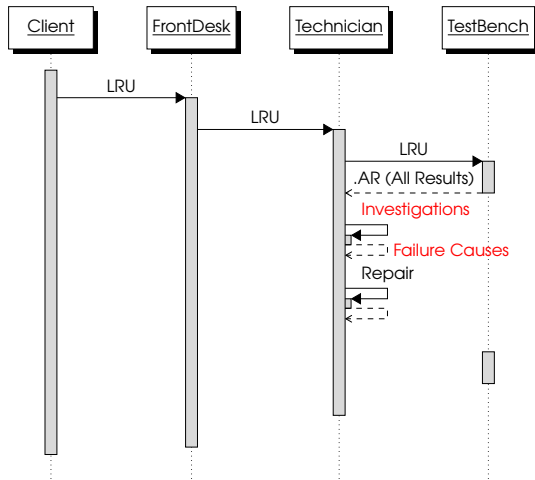


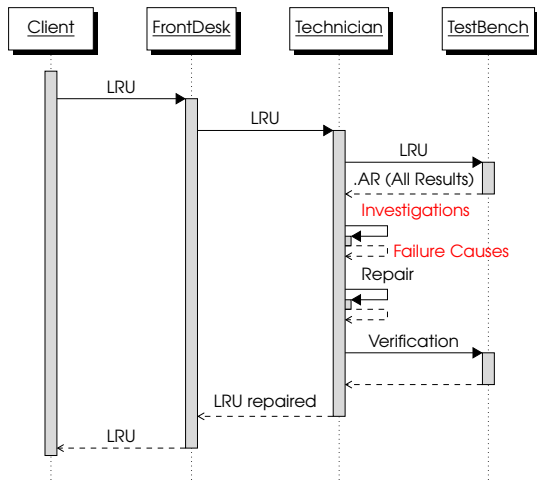
Our work concerns levels 2 and 3, i.e **in shop** maintenance.

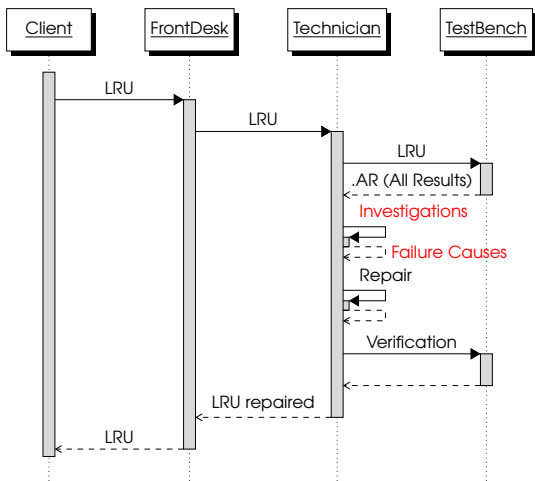








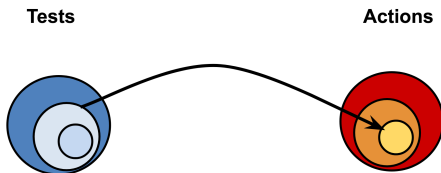




The **signature of a failure** provides all the **necessary information** to understand, identify and ultimately repair a failure.

Objective : From an application point of view

Support avionics maintenance by discovering Failure Signatures and proposing corrective actions, in such a way that the suggestions are explainable.



Problematic

Our problem has the following constraints:

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- **Sparse data:** We can not rely on techniques that require large amounts of data to model a process (150 samples).
- **No explicit model knowledge:** for the diagnose process.
- **Number of suggested repair actions:** The suggested components to be replaced should be minimized.
- **Provide an explanation for the given results:** Explainability of the system is important for technicians and security certification.

Objective : From a theoretical point of view

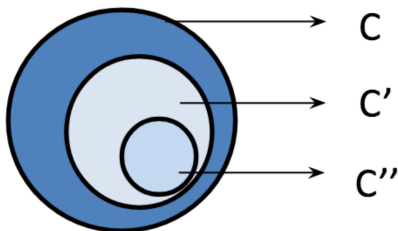
- Modeling the domain in a formal (\mathcal{ELO}) ontology
- Discovering concepts represent failure signatures that allow us to associate repair actions

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Intuition

Concept Refinement



Representative Concept

Definition (A representative concept)

\mathcal{O} : an ontology, Δ : the set of individuals in \mathcal{O} .

Let $\mathcal{X} \subseteq \Delta$. For a concept C , we say that \mathcal{X} is **represented** by C if:

$\mathcal{O} \models C(x)$ for all $x \in \mathcal{X}$, and

$\mathcal{O} \not\models C(y)$ for any $y \in \Delta \setminus \mathcal{X}$.

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Proposition

Representability_C:

Does C represent \mathcal{X} w.r.t. \mathcal{O} ?

*can be solved in **PTime**.*

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Does C represent \mathcal{X} w.r.t. \mathcal{O} ?

*can be solved in **PTime**.*

Representability_n:

Is there a concept C with $|C| < n$ that represents \mathcal{X} w.r.t. \mathcal{O} ?

*is **ExpTime**. If n is bounded by a constant, then Representability_n is in **PTime**.*

Situation Discovery

The concepts representing a set \mathcal{X} are equivalent in the sense of their instances.

We call each of these equivalent classes a **situation** in \mathcal{O} .

Definition (Situation in \mathcal{O})

\mathcal{O} : an ontology; Δ : the set of individuals in \mathcal{O} ; $\mathcal{X} \subseteq \Delta$.

A **situation** for \mathcal{X} in \mathcal{O} is the set:

$$\|\mathcal{X}\|_{\Delta}^{\mathcal{O}} = \{C \mid C \text{ represents } \mathcal{X} \text{ w.r.t. } \mathcal{O} \text{ and } \Delta\}.$$

Situation Discovery - All Situations

Definition (SD_n)

\mathcal{O} : an ontology; Δ : the set of individuals in \mathcal{O} ; $\mathcal{X} \subseteq \Delta$; $n > 0$;

SD_n : Does there exist a situation C for **some** $\mathcal{X}' \subseteq \mathcal{X}$ in \mathcal{O} with $|C| \leq n$?

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SD_n is in **ExpTime**. If $|\mathcal{X}|$ and n are bounded by a constant, SD_n is in **PTime**.

Situation Discovery - All Situations

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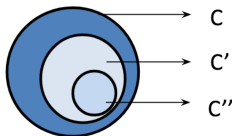
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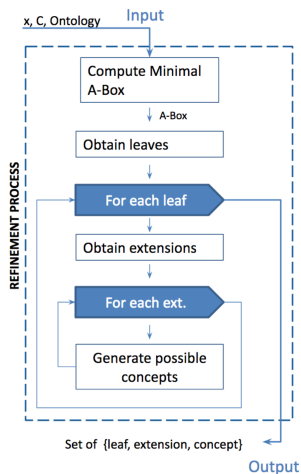
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SD_n is in **ExpTime**. If $|\mathcal{X}|$ and n are bounded by a constant, SD_n is in **PTime**.

\rightsquigarrow An **algorithm** for finding situations for a set of individuals



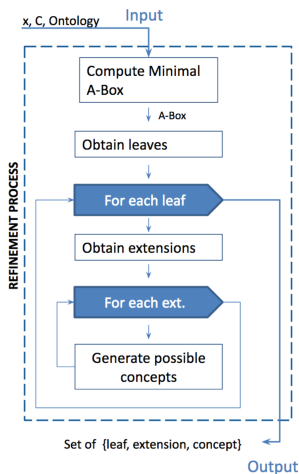
Refinement Algorithm Overview - Steps to refine a concept C 

Consider:

$$C \equiv \exists r_1.T$$

$$ABox = \{r_1(x, y), A(y), r_2(x, z), B(z)\}$$

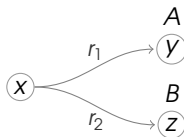
Refinement Algorithm Overview - Steps to refine a concept C



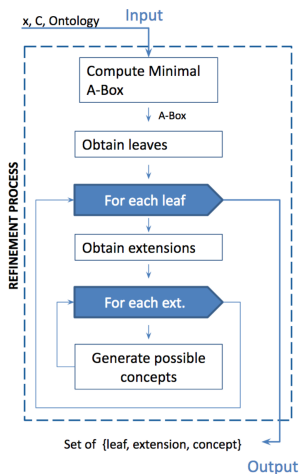
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The graph representation of x :

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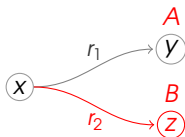


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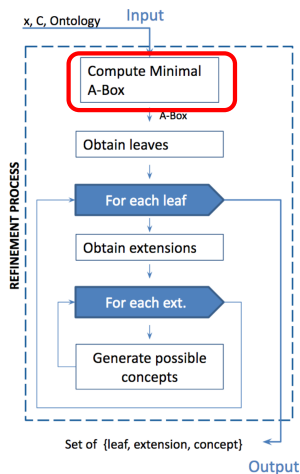
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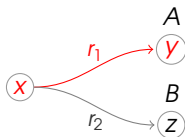
Some assertions are **unnecessary**

Refinement Algorithm Overview - Steps to refine a concept C 

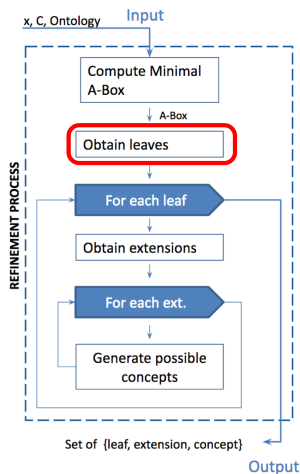
Consider:

$$C \equiv \exists r_1. \top$$

$$ABox = \{r_1(x, y), A(y), r_2(x, z), B(z)\}$$

We can extract those **necessary** assertions

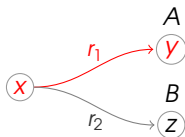
$$\text{Minimal } ABox = \{r_1(x, y)\}$$

Refinement Algorithm Overview - Steps to refine a concept C 

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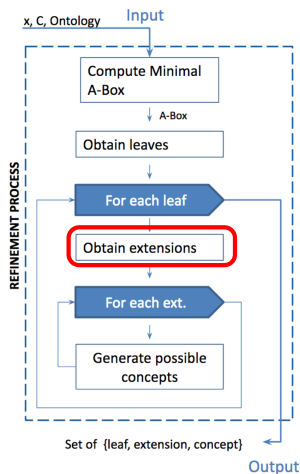
$$ABox = \{r_1(x, y), A(y), r_2(x, z), B(z)\}$$



$$\text{Minimal ABox} = \{r_1(x, y)\}$$

$$\text{Leaves}_{x,C} = \{x, y\}$$

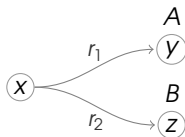
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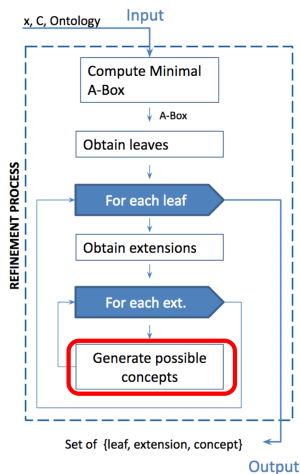
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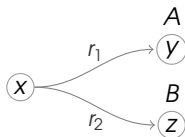
$$\text{Ext}_{x,C} = \{r_2(x, z), A(y)\}$$

Refinement Algorithm Overview - Steps to refine a concept C 

Consider:

$$C \equiv \exists r_1. \top$$

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$$\text{Minimal } ABox = \{r_1(x, y)\}$$

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$$\text{Ext}_{x,C} = \{r_2(x, z), A(y)\}$$

$$C'_1 \equiv \exists r_1. \top \cap \exists r_2. \top$$

$$C'_2 \equiv \exists r_1. (\top \cap A)$$

The Most Specific Representative (MSR)

Definition (Most Specific Representative MSR)

Given a set of individuals $\mathcal{X} = \{x_1, \dots, x_n\}$ and the set of its representative concepts $||\mathcal{X}|| = \{\mathcal{S} \mid \mathcal{S} \text{ represents } \mathcal{X}\}$, the **Most Specific Representative** of the set \mathcal{X} , written $\text{MSR}_{\mathcal{X}}$, is the concept $\mathcal{S}_i \in ||\mathcal{X}||$ such that:

$$\forall \mathcal{S}_j \in ||\mathcal{X}||, \text{ we find } \mathcal{S}_i \sqsubseteq \mathcal{S}_j.$$

Summary

We have provided definitions, specifications and algorithms to:

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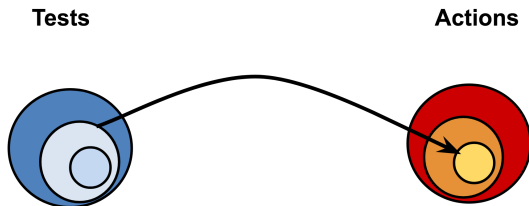
We have provided definitions, specifications and algorithms to:

- Obtain the refinements of a concept C .
- Obtain the MSR for an individual x .
- Obtain the MSR for a set \mathcal{X} of individuals.
- Discover and characterize all situations present in an ontology \mathcal{O} .

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Intuition



The Data Sources - .AR files

```

=====
=
= 8: ARINC INPUTS/OUTPUTS =
=
=====
  
```

► Part/Chapter

ARINC MESSAGE RECEPTION

=====

► Function

180203	T1DGI008	080030	40AC	HEX	EQ	40AC	GO
180206	T1DGI008	080040	50AC	HEX	EQ	40AC	NOGO

COM ARINC reception CHANNEL1)

► Sub-function

180215	T1DGI008	080050	A00000	HEX	EQ	D55555	NOGO
180221	T1DGI008	080330	D55555	HEX	EQ	D55555	GO
180227	T1DGI008	080620	D55555	HEX	EQ	D55555	GO

Code

Designation

Measurements

Result / Sanction

Figure: An extraction of the structure of an .AR file.

The Data Sources - Corrective Actions

Corrective actions for **Elevator and Aileron Computer (ELAC)** .
We distinguish between **composed** and **individual** actions.

Ar File	SRU1 Type	SRU1 Component	SRU1 repere topo
20094-777-777.AR	MPU ANA	AMPLI	U30 U44
20182-777-777.AR	MSP DG	EPLD	U28
20030-777-777.AR	MSP DG	EPLD RAM	U25 U35 U36

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20030-777-777.AR	MSP DG	EPLD RAM	U25 U35 U36

□ ELAC Boards

6 boards

PS2
Power Supply

MPU-ANA
Processor / Analog

MSP-DG
Processor / Digital

CSP-DG
Processor / Digital

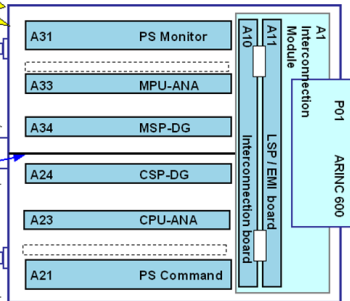
CPU-ANA
Processor / Analog

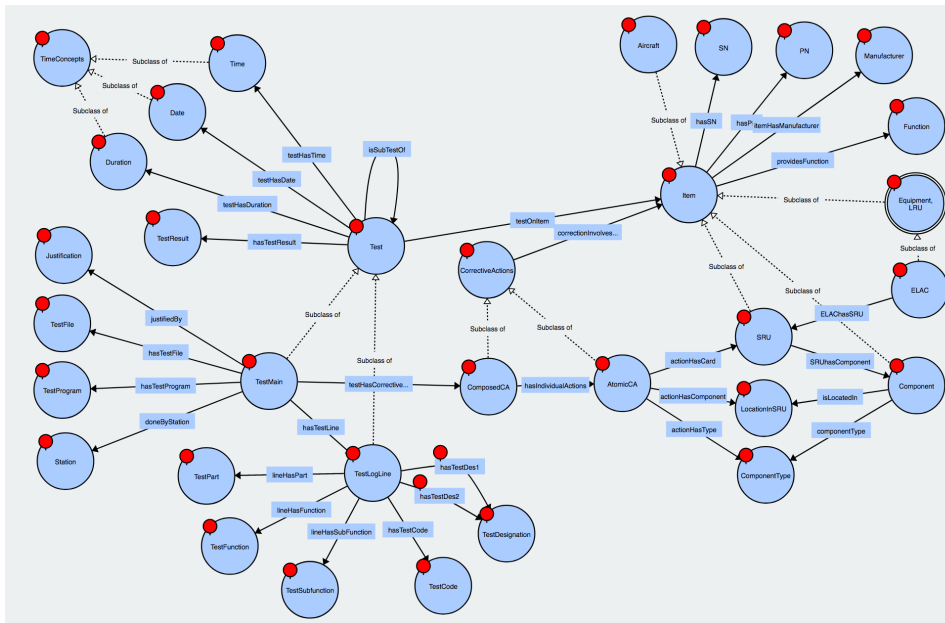
PS1
Power Supply

MON boards

Metal plate segregation

COM boards





Situations in Avionics Maintenance

The **.AR files become the individuals** we want to distinguish.

Definition (Signature in \mathcal{O})

Given a set of .AR files $\{f_1, \dots, f_n\}$ and an ontology \mathcal{O} , the **signature** \mathcal{S} of $\{f_1, \dots, f_n\}$ is their MSR.

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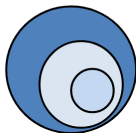
Definition (Most Specific Signature)

Given an .AR file f_x and an ontology \mathcal{O} that contains learned signatures. Let $f_x \in \mathcal{S}_1, \dots, \mathcal{S}_n$ be the signatures for f_x . A **most specific signature** for f_x is defined by:

$$\mathcal{S}_{f_x} = \{\mathcal{S}_i \mid \nexists \mathcal{S}_j \text{ with } \mathcal{S}_j \subset \mathcal{S}_i\}$$

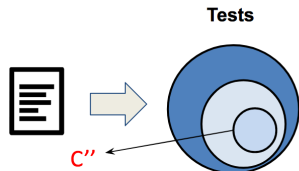
Consult - Overview

Tests



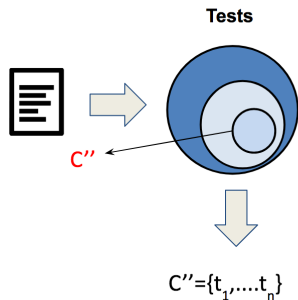
The KB is trained with historical data to **learn the signatures**.

Consult - Overview



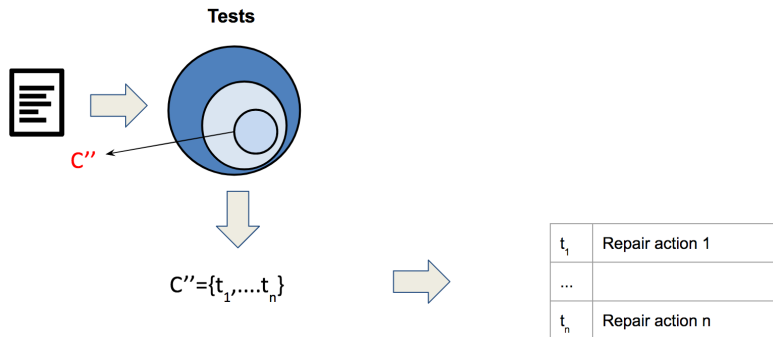
With the signatures available, we can **classify** new, unseen .AR files.

Consult - Overview



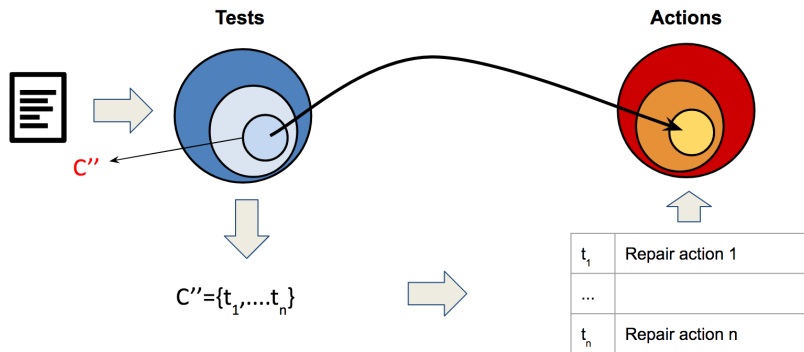
For each signature a set of files is **associated**.

Consult - Overview



The historical data tells us **the corresponding corrective actions**.

Consult - Overview



These actions become **the suggestions** for the technician.

Consult the KB - HMI

e-Diag Home Upload Feedback

THALES

Our suggestions for '011414-11-21-10h25.AR' file

#1 Confidence: 65 %

Positive = 17 / 50

#	Event	Board	Location	Type
1	✕	CARTE CSP-DG	U18	AMPLI

#2 Confidence: 20 %

Positive = 9 / 50

#	Event	Board	Location	Type
1	✕	CARTE CSP-DG	U22	AMPLI
2	✕	CARTE CSP-DG	U25	EPLD

#3 Confidence: 15 %

Positive = 24 / 50

#	Event	Board	Location	Type
1	✕	CARTE MSP-DG	Q65	AMPLI

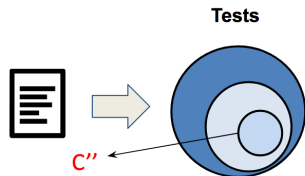
NEW UPLOAD

Figure: The suggested corrective actions for the consulted file.

Feedback - Overview

Two main tasks on the feedback process:

- **Integrate new corrective actions:** added to the historical data.



Feedback - Overview

Two main tasks on the feedback process:

- **Integrate new corrective actions:** added to the historical data.
- **Discover new signatures:** **incrementally enrich** the knowledge base (ontology).

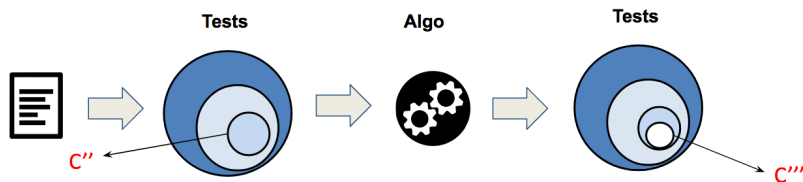


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Similar Approaches - DL-learner

Actions Per File - DL-Learner vs. TAMO

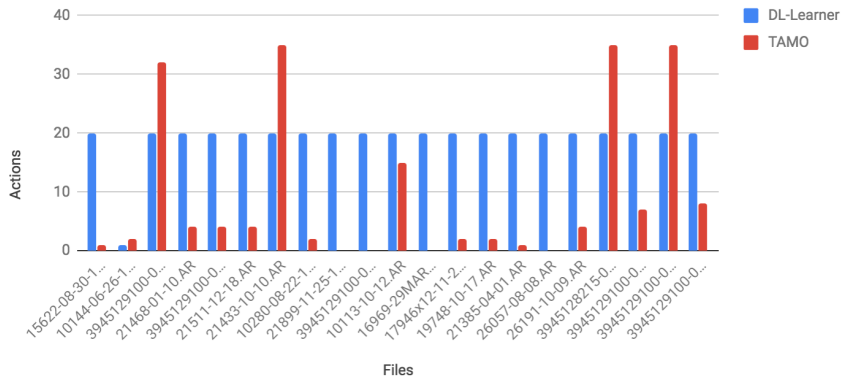


Figure: The less number of actions the better.

Relevance and Specificity of the Suggestions by TAMO

X-axis: each consulted file

Y-axis: the number of relevant individual actions



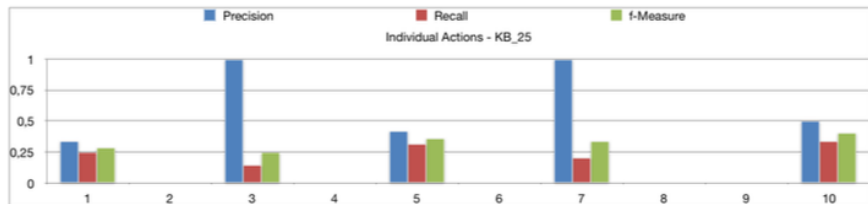
Figure: The suggestions for the test files, when consulting the knowledge base learned from 100 files. In the figure are shown the correct atomic actions (green) and the correct composed actions (orange).

Note that: only 30% of the files have the possibility to be correctly classified due to data sparsity.

Evolution of the KB - Number and Specificity of Signatures

X-axis: each signature

Y-axis: the valued of Precision/Recall/F-score

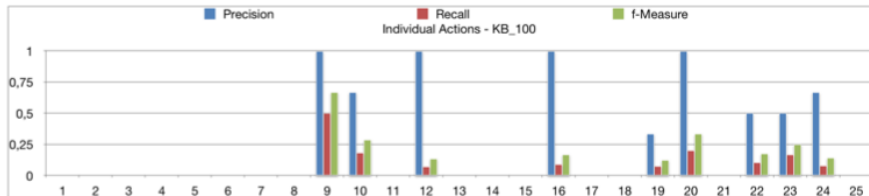
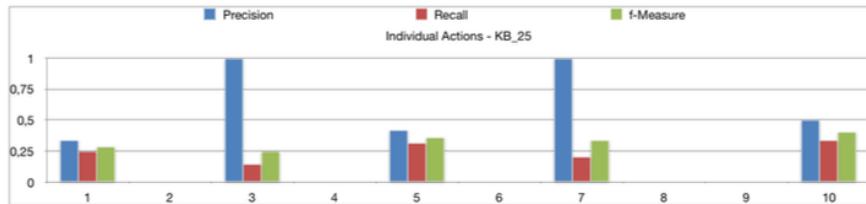


- 50 files consulted against a knowledge base trained with 25 files.

Evolution of the KB - Number and Specificity of Signatures

X-axis: each signature

Y-axis: the valued of Precision/Recall/F-score



- 50 files consulted against a knowledge base trained with 25 files.
- 50 files consulted against a knowledge base trained with 100 files.

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Application to an Avionics Maintenance task by **characterizing failure signatures** as that of discovering situations.

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Application to an Avionics Maintenance task by **characterizing failure signatures** as that of discovering situations.

More expressive DLs The current approach in $\mathcal{EL}\mathcal{O}$. Natural extensions to be considered are disjunction (\sqcup) and negation (\neg).

Conclusions

We have formally defined the **situation discovery problem** and provided **upper bounds** and **algorithms** to compute them.

The discovered concepts provide **a meaningful description** of the main features shared by the individuals in the situation.

Application to an Avionics Maintenance task by **characterizing failure signatures** as that of discovering situations.

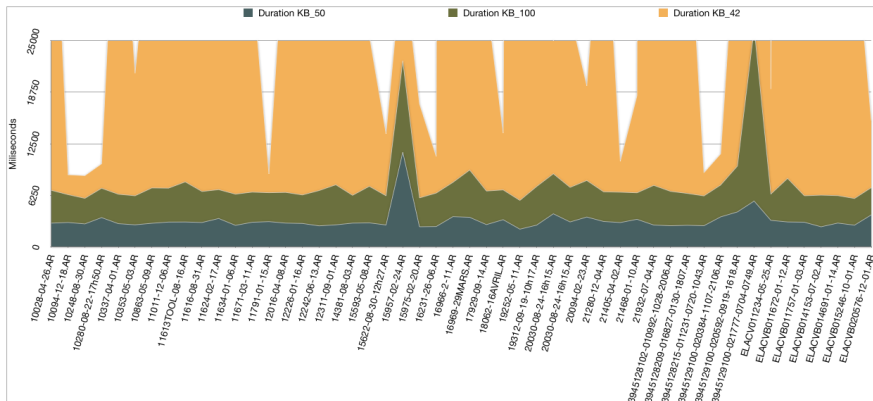
More expressive DLs The current approach in $\mathcal{EL}\mathcal{O}$. Natural extensions to be considered are disjunction (\sqcup) and negation (\neg).

Parallel Processing The modifications made split the ABox in several consistent partitions. Each ABox can be consulted by a separate process (i.e. parallel processing) and then aggregate the results.

Thanks for your attention

Response Times

50 files consulted against V1 and V2 of the prototype.



- On the background the consult time using V1 (KB trained with 50 files).
- On the front most the consult time with V2 (KB trained with 50 files).
- On the middle (green) consult time V2 (KB trained with 100 files).