

# *Interferometric Phase Image Estimation via Sparse Coding in the Complex Domain*

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# Outline

1. The phase estimation problem
2. Examples in InSAR and in MRI
3. Phase unwrapping
4. Interferometric phase estimation via sparse coding
5. Non-Gaussian and non-additive noise
6. Concluding remarks

# Absolute Phase Estimation problem

Given a set of observations  $e^{j\phi_p} \equiv (\cos \phi_p, \sin \phi_p)$ ,  
for  $p \in \mathcal{V} \equiv \{1, \dots, n\}$ , determine  $\phi_p$  (up to a constant)

$e^{j\phi_p}$  is  $2\pi$ -periodic  $\Rightarrow$  nonlinear and ill-posed inverse problem

**Continuous/discrete flavor:**  $\phi = \mathcal{W}[\phi] + 2k\pi \quad \mathcal{W} : \mathbb{R} \rightarrow [\pi, \pi[$

**Phase Unwrapping (PU)**



Estimation of  $k \in \mathbb{Z}$

**Phase Denoising (PD)**

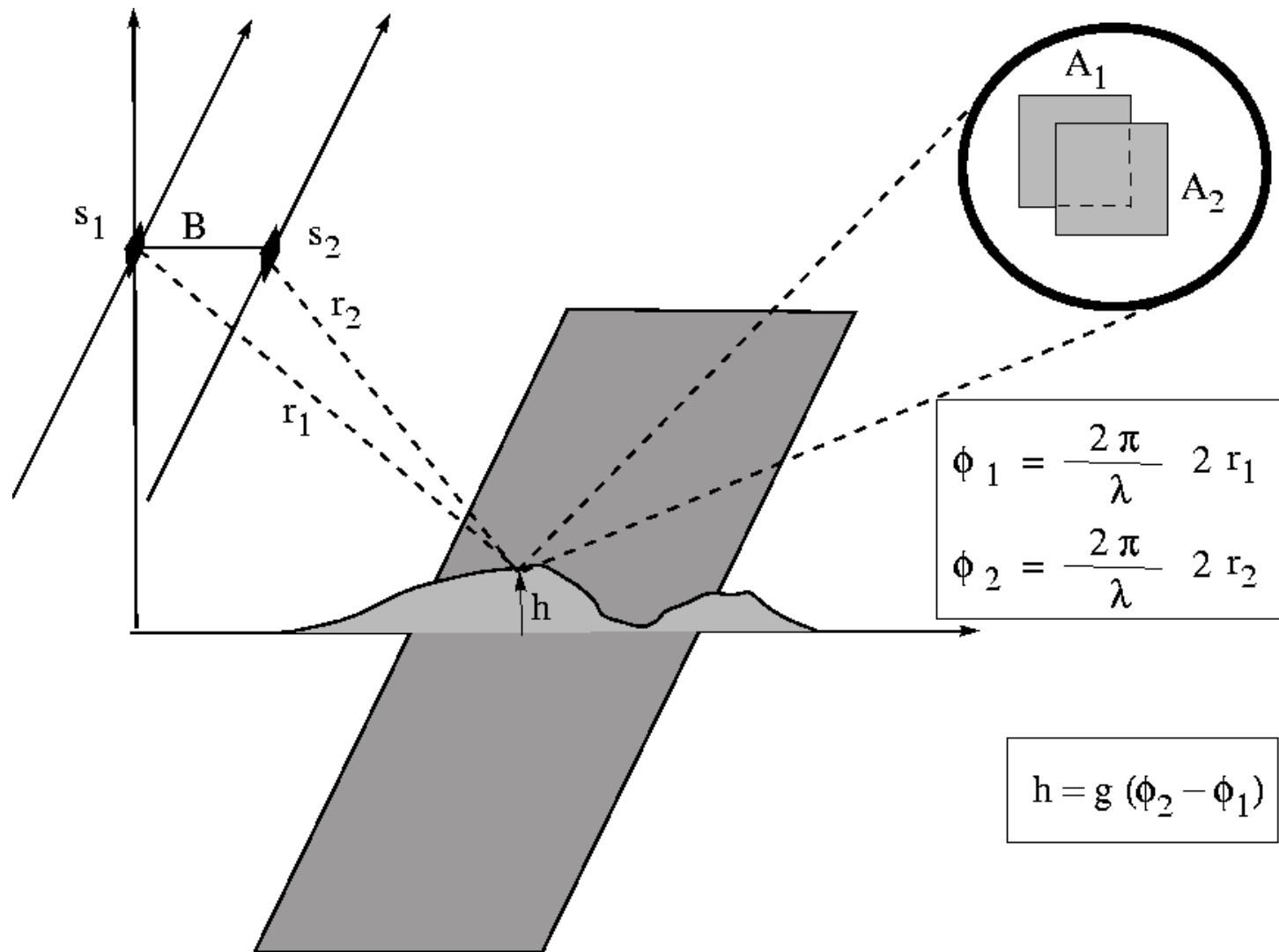


Estimation of  $\mathcal{W}(\phi) \in [\pi, \pi[$   
(wrapped phase)

# Applications

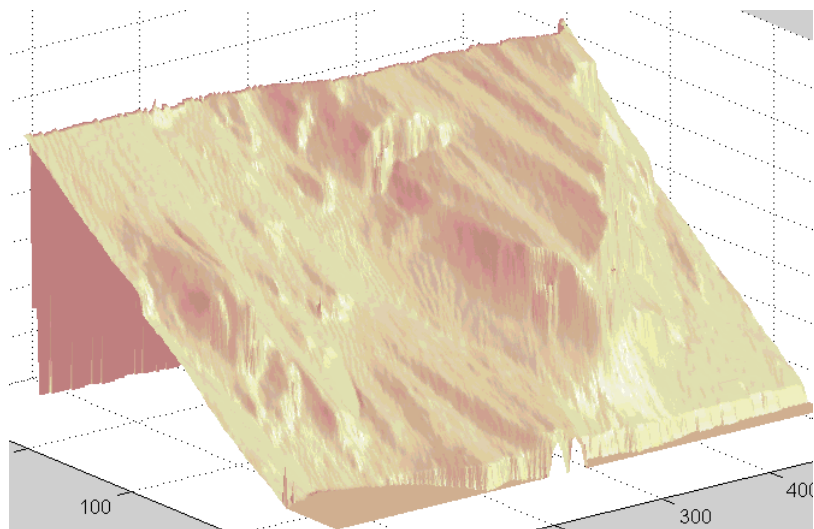
- ❑ Synthetic aperture radar/sonar
- ❑ Magnetic resonance imaging
- ❑ Doppler weather radar
- ❑ Doppler echocardiography
- ❑ Optical interferometry
- ❑ Diffraction tomography

# Absolute Phase Estimation in InSAR (Interferometric SAR)

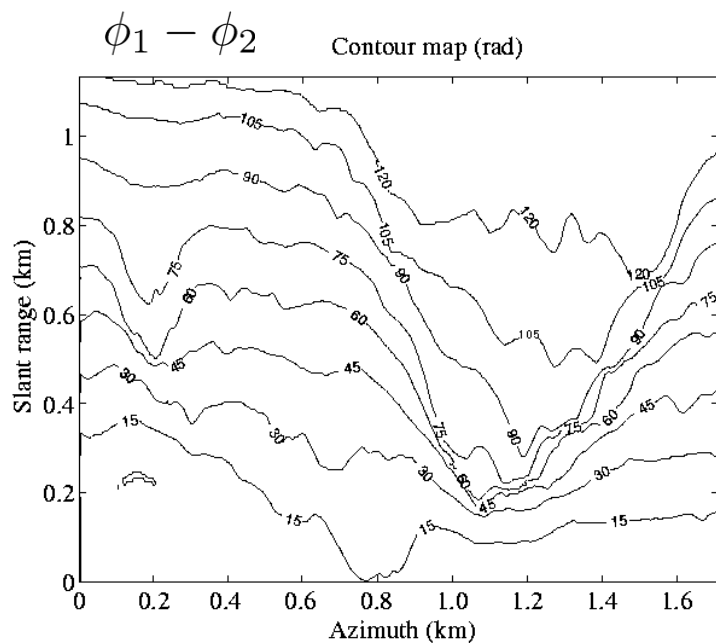


**InSAR Problem:** Estimate  $\phi_2 - \phi_1$  from signals read by  $s_1$  and  $s_2$

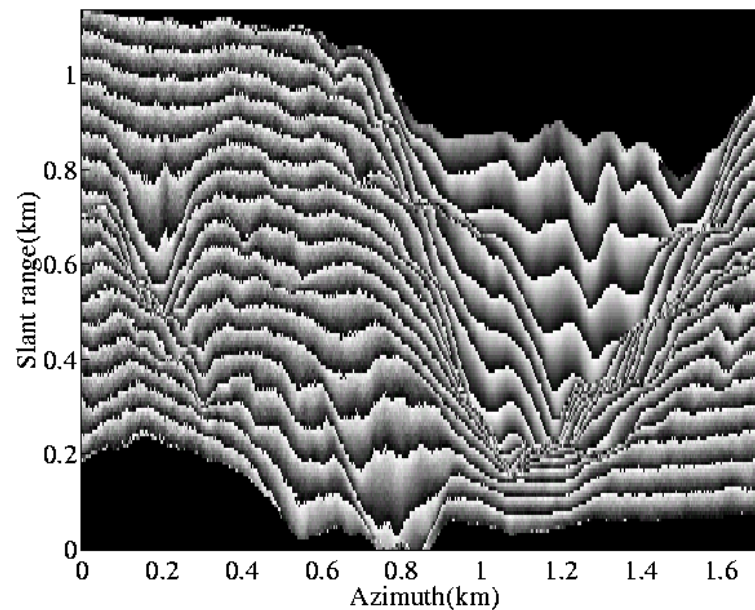
# InSAR Example



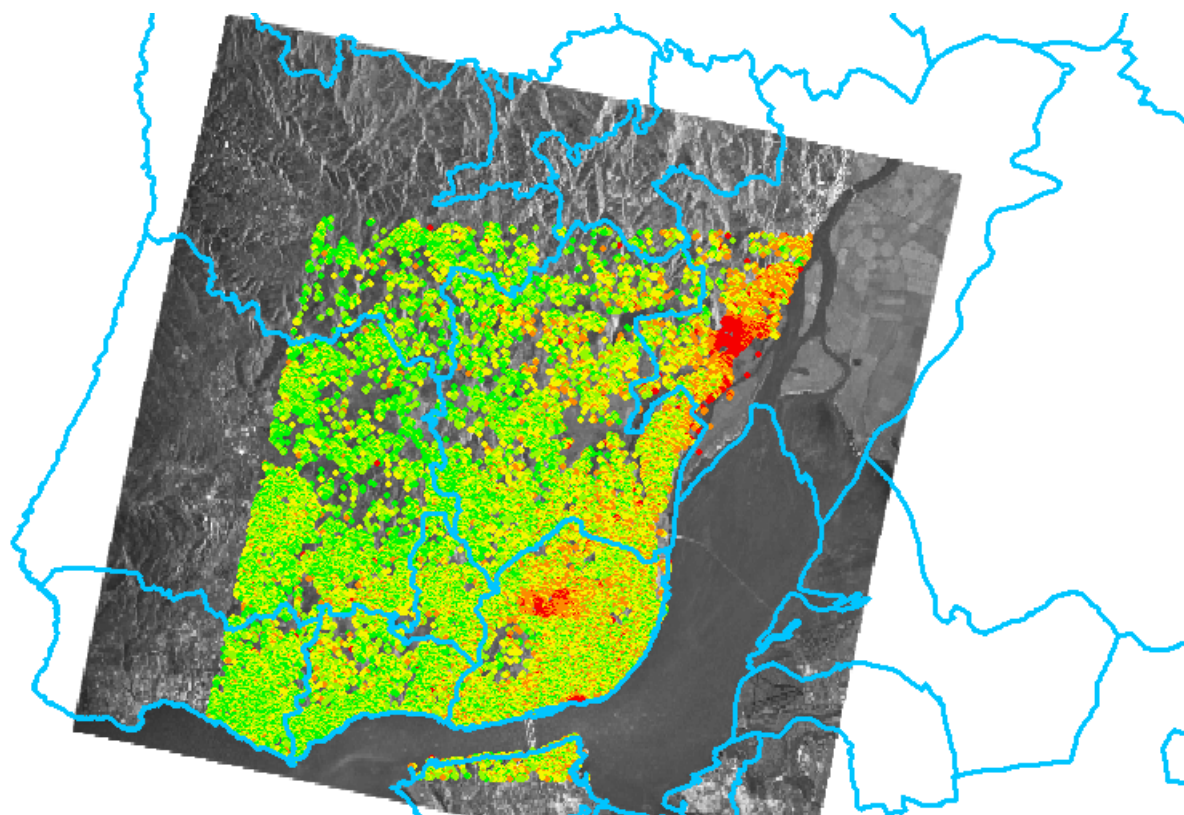
Mountainous terrain around  
Long's Peak, Colorado



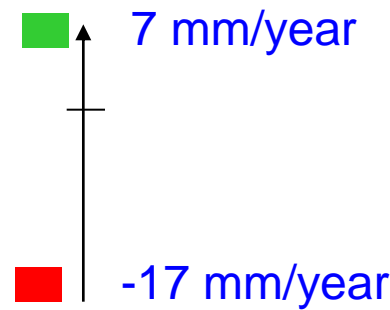
Interferogram  $\mathcal{W}(\phi_1 - \phi_2)$



# Differential Interferometry

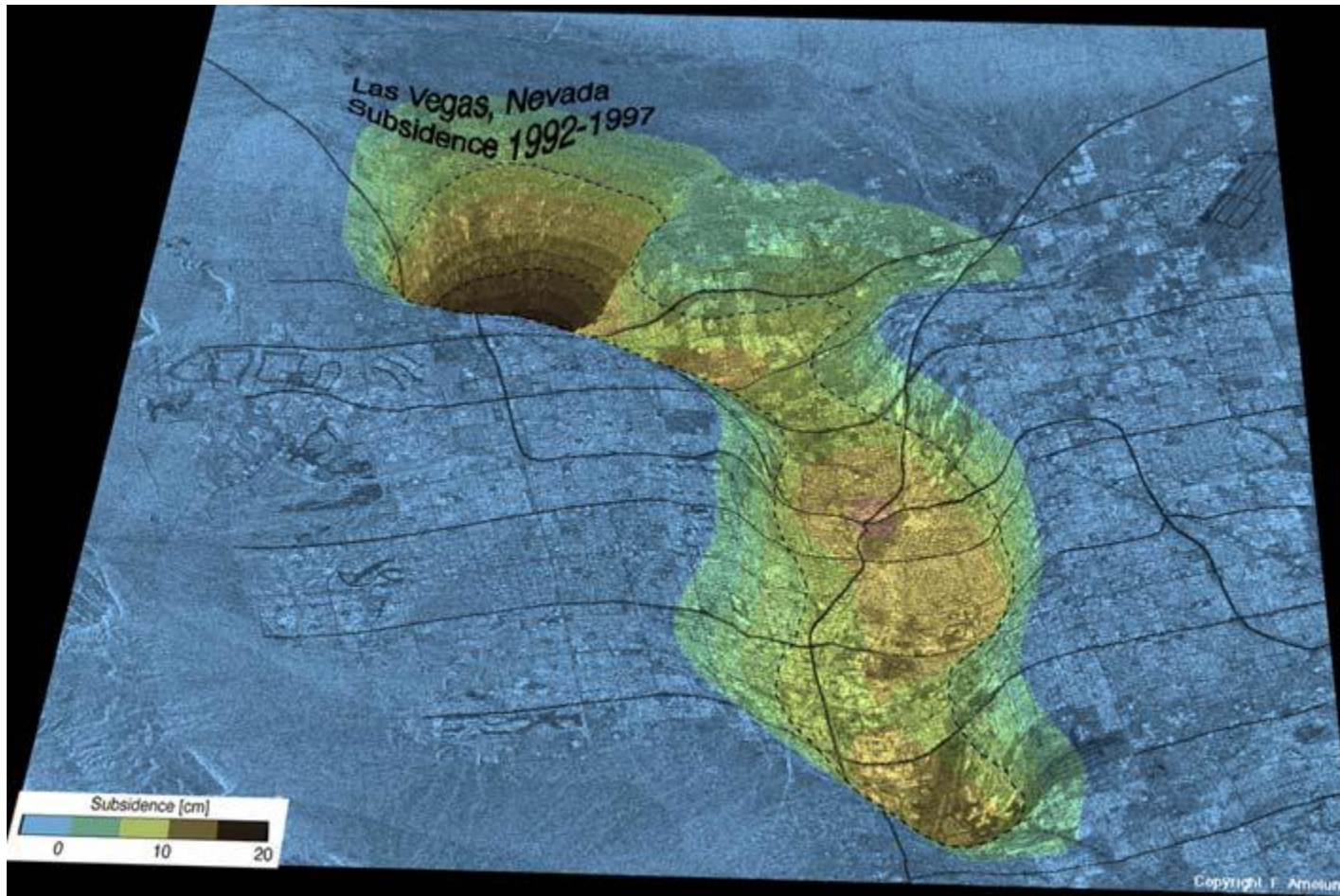


Height variation





# Differential Interferometry

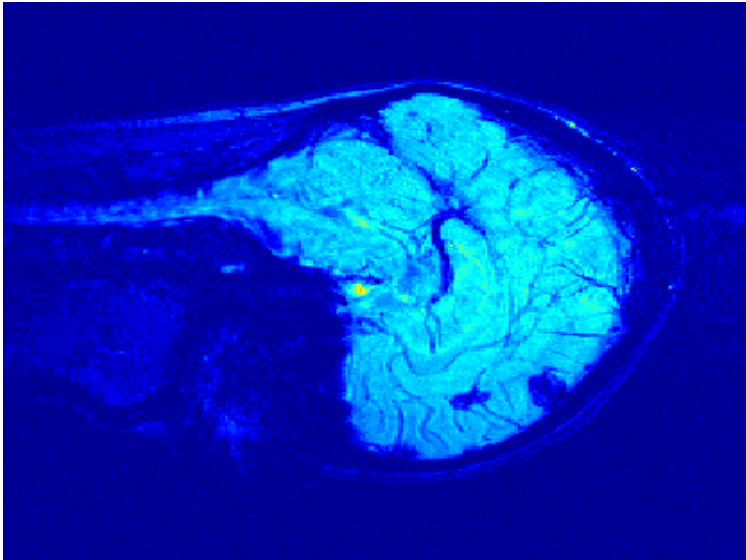


Differential InSAR derived subsidence in Las Vegas between 1992 and 1997 (from [Amelung et al., 1999]).

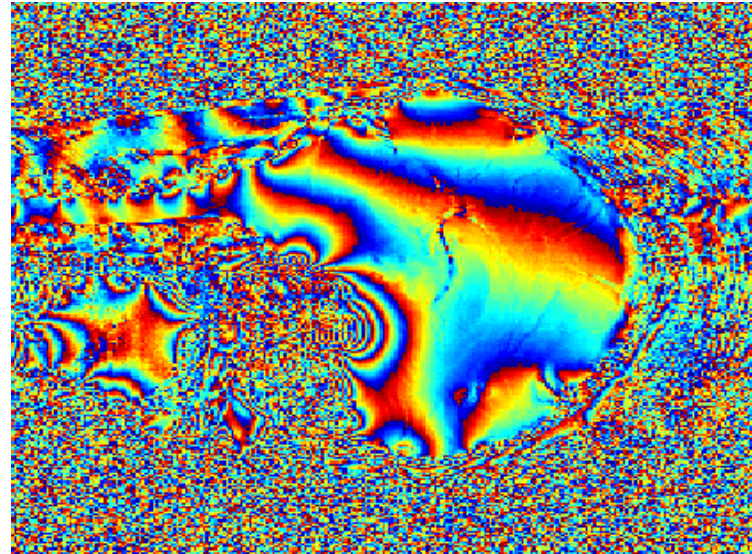


# Magnetic Resonance Imaging - MRI

Intensity



Interferometric phase



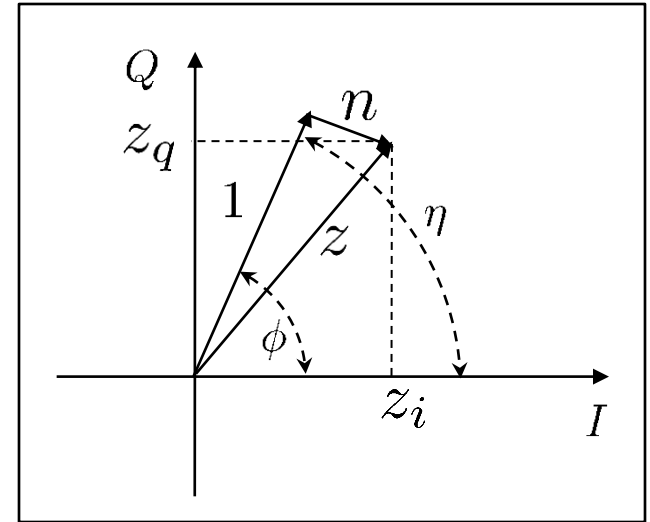
## Interferometric phase

- measure temperature
- visualize veins in tissues
- water-fat separation
- map the principal magnetic field

# Forward Problem: Sensor Model

$$\begin{aligned} z_i &= \cos \phi + n_i & n &= (n_i, n_q) \\ z_q &= \sin \phi + n_q & z &= (z_i, z_q) \end{aligned}$$

$$(n_i, n_q) \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_2)$$



$$p(z|\phi) \propto c e^{\lambda \cos(\phi - \eta)}$$



$$\hat{\phi}_{ML} = \eta + 2k\pi$$

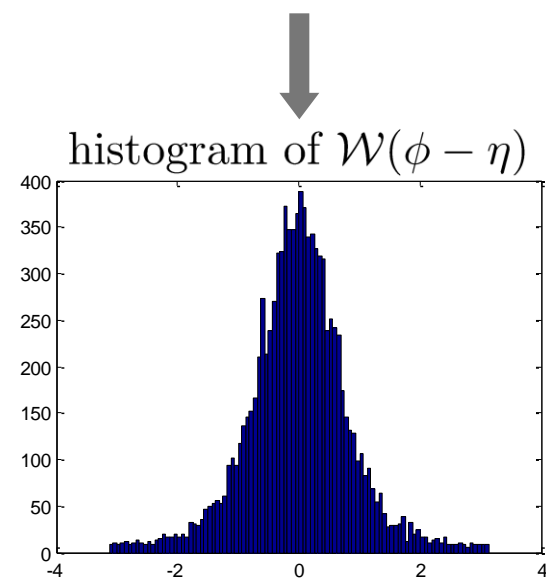
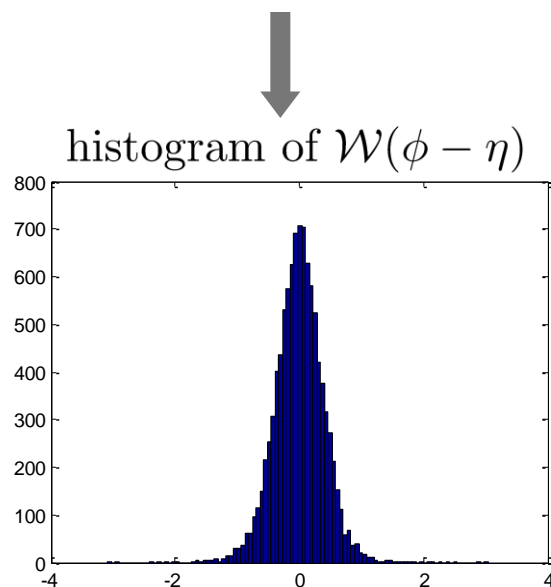
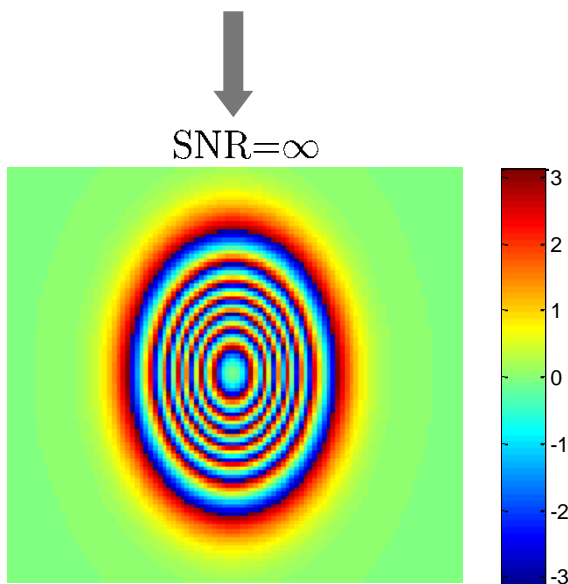
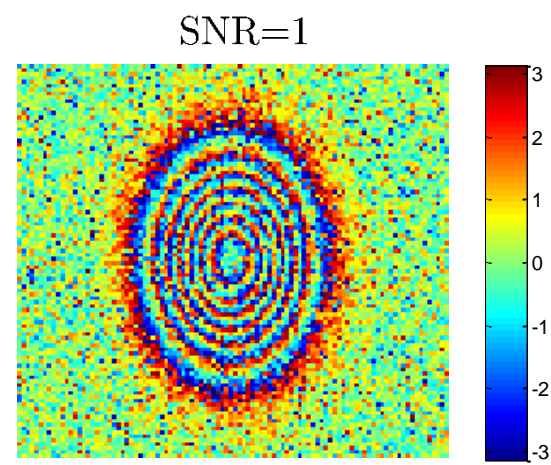
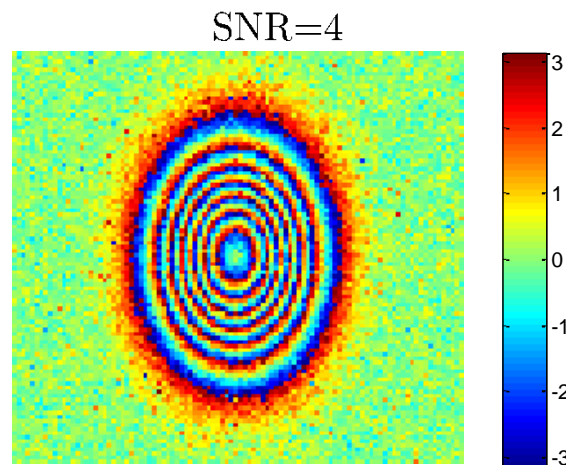
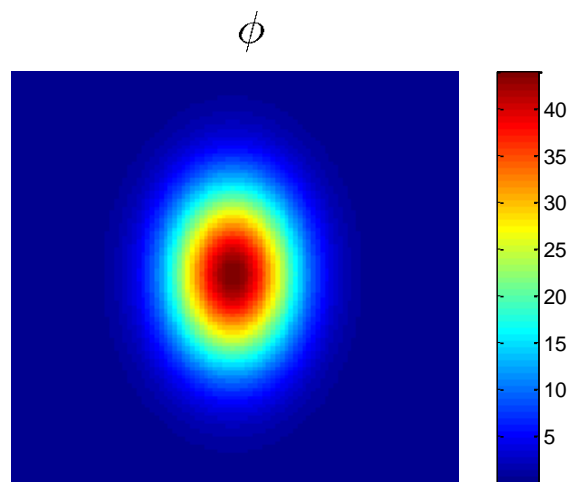
$$\eta = \arg(z)$$

$$\lambda = \frac{2|z|}{\sigma^2}$$

# Simulated Interferograms

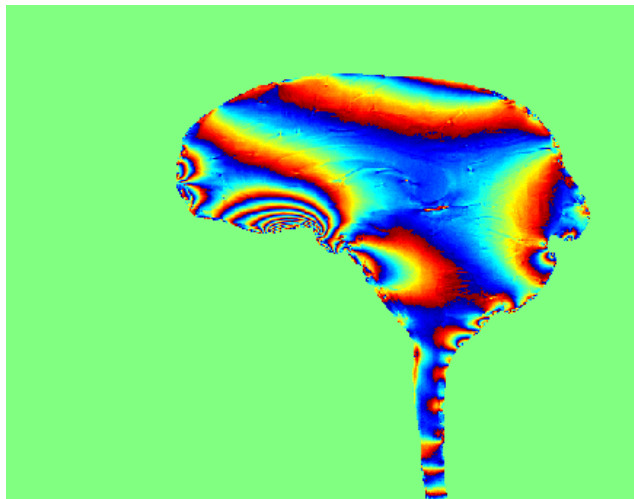
Images of  $\eta = \arg(e^{j\phi} + n)$

$$\text{SNR} \equiv \frac{1}{2\sigma^2}$$

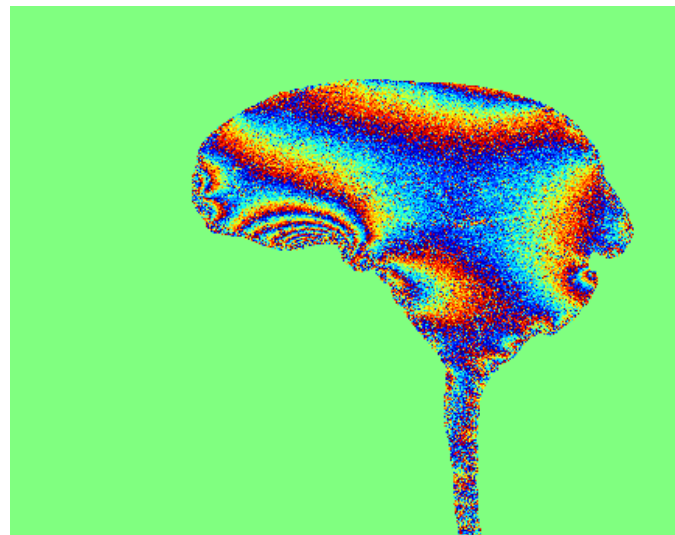


# Real Interferograms

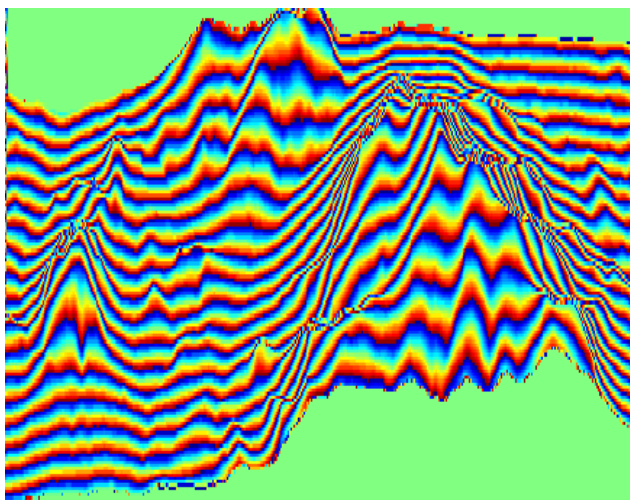
MRI



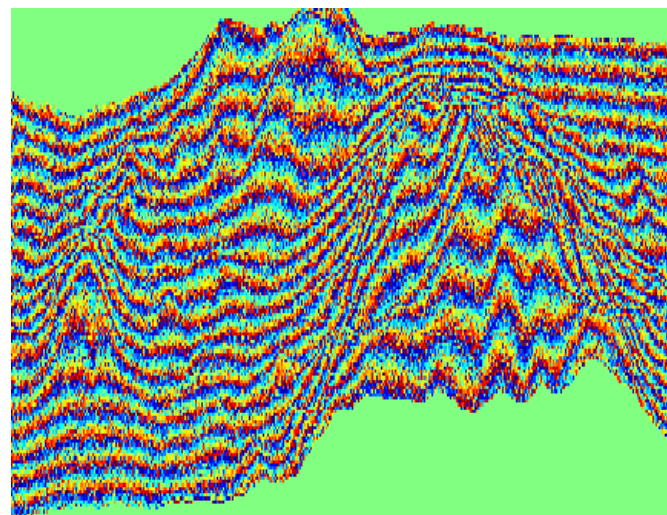
MRI



InSAR



InSAR



# Bayesian Approach

data density:  $p(\mathbf{z}|\phi) = \prod_{p \in \mathcal{V}} p(z_p|\phi_p)$

prior (MRF):  $p(\phi) = \frac{1}{Z} e^{-\sum_{\{p,q\} \in \mathcal{E}} E_{pq}(\phi_p - \phi_q)}$

- $\mathcal{E} = \{\{p, q\} : p \sim q\}$  clique set
- $E_{pq}(\cdot)$  clique potential (pairwise interaction)

$E_{pq}(\cdot)$  convex



Enforces smoothness

$E_{pq}(\cdot)$  non-convex



Enforces piecewise smoothness  
(discontinuity preserving)

# Maximum a Posteriori Estimation Criterion

$$\square \quad \hat{\phi} \in \arg \max_{\phi \in \mathbb{R}^n} p(\phi|\mathbf{z}) \quad p(\phi|\mathbf{z}) \propto p(\mathbf{z}|\phi) p(\phi) \quad \text{posterior density}$$

$$= \arg \min_{\phi} E(\phi) \quad E(\phi) = -\log p(\phi|\mathbf{z}) + c^{te}$$

$$E(\phi) = \sum_{p \in \mathcal{V}} -\lambda_p \cos(\phi_p - \eta_p) + \sum_{\{p,q\} \in \mathcal{E}} E_{pq}(\phi_p - \phi_q)$$

$\square$  Phase unwrapping (  $\lambda_p \rightarrow \infty$  ):

$$\phi_p = \eta_p + 2k_p\pi \quad \text{for } k_p \in \{0, 1, \dots, K-1\}$$

$$\hat{\phi} \in \arg \min_{\mathbf{k} \in \mathbb{Z}^n} E(\mathbf{k}) \quad E(\mathbf{k}) = \sum_{\{p,q\} \in \mathcal{E}} V_{pq}(k_p - k_q)$$

$$V_{pq}(k_p - k_q) = E_{pq}(\eta_p - \eta_q + 2\pi(k_p - k_q))$$

# Phase Unwrapping Algorithms

$$E(\mathbf{k}) = \sum_{\{p,q\} \in \mathcal{E}} V_{pq}(k_p - k_q)$$

- $E_{pq}(\cdot) = |\cdot|_{2\pi\text{-quantized}}$

[Flynn, 97] (exact) → sequence of positive cycles on a graph

[Costantini, 98] (exact) → min-cost flow on a graph ( $|\mathcal{V}| = n, |\mathcal{E}| = 4n$ )

- $E_{pq}(\cdot) = (\cdot)^2$

[B & Leitao, 01] (exact) → sequence of positive cycles on a graph ( $|\mathcal{V}| = n, |\mathcal{E}| = 4n$ )

[Frey et al., 01] (approx) → belief propagation on a 1st order MRF

- $E_{pq}(\cdot)$  convex

[B & Valadao, 05,07,09] (exact) → Sequence of  $K$  min cuts ( $KT(n, 6n)$ )

- $E_{pq}(\cdot)$  non-convex

[Ghiglia, 96] → LPN0 (continuous relaxation)

[B & G. Valadao, 05, 07,09] → Sequence of min cuts ( $KT(n, 6n)$ )



# PUMA (Phase Unwrapping MAx-flow)

[B & Valadao, 05,07,09]

$$\phi^{(0)} = \eta$$

**while** success == false

$$\delta' := \arg \min_{\delta \in \{0,1\}^{|\mathcal{V}|}} E(\phi + 2\delta\pi)$$

**if**  $E(\phi + 2\delta'\pi) < E(\phi)$  **then**  $\phi := \phi + 2\delta'\pi$

**else** success = true

**end**

PUMA finds a sequence of steepest descent binary images

# PUMA: Convex Priors

- ❑ A local minimum is a global minimum
- ❑ Takes at most  $K$  iterations
- ❑  $E$  is submodular:  $2V_{pq}(0) \leq V_{pq}(1) + V_{pq}(-1)$

$\Rightarrow$  each binary optimization has the complexity  
of a min cut  $T(n, 6n)$

$$E(\mathbf{k}) = \sum_{p \in \mathcal{V}} U_p(k_p) + \sum_{\{p,q\} \in \mathcal{E}} V_{pq}(k_p - k_q)$$

- ❑ Related algorithms

[Veksler, 99] (1-jump moves )

[Murota, 03] (steepest descent algorithm for L-convex functions)

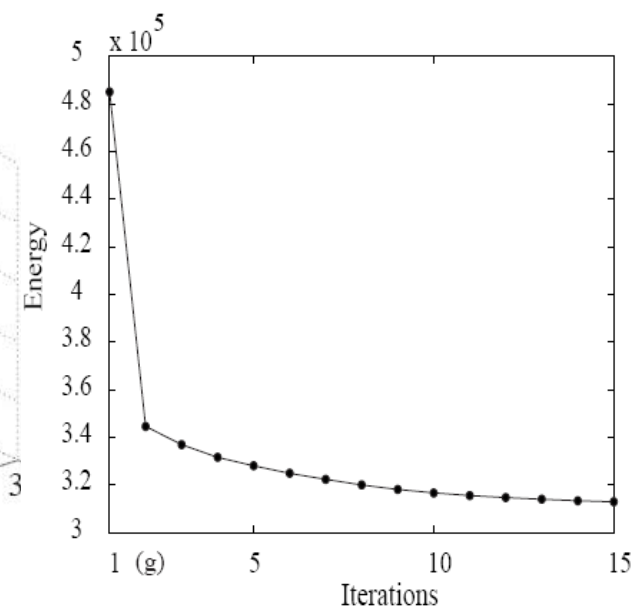
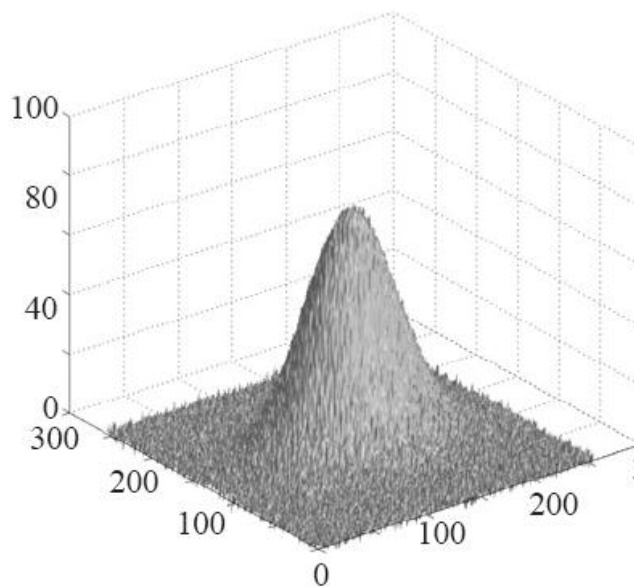
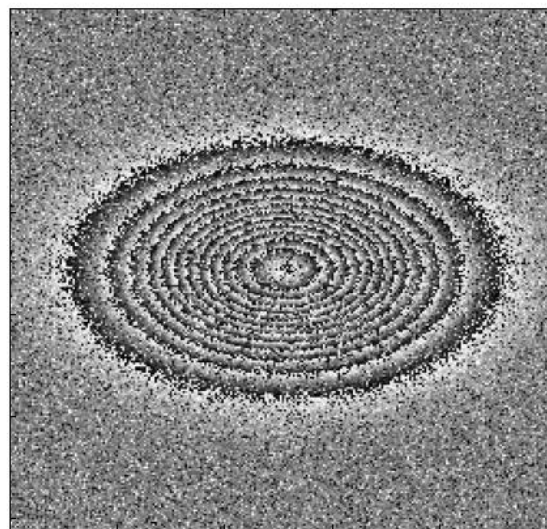
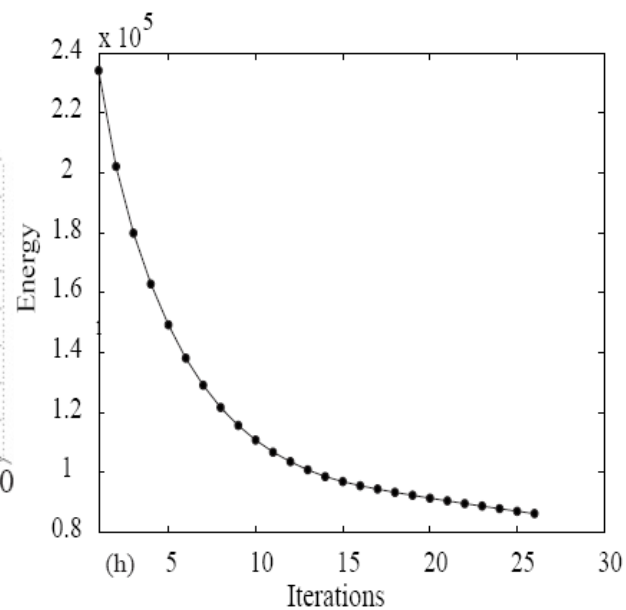
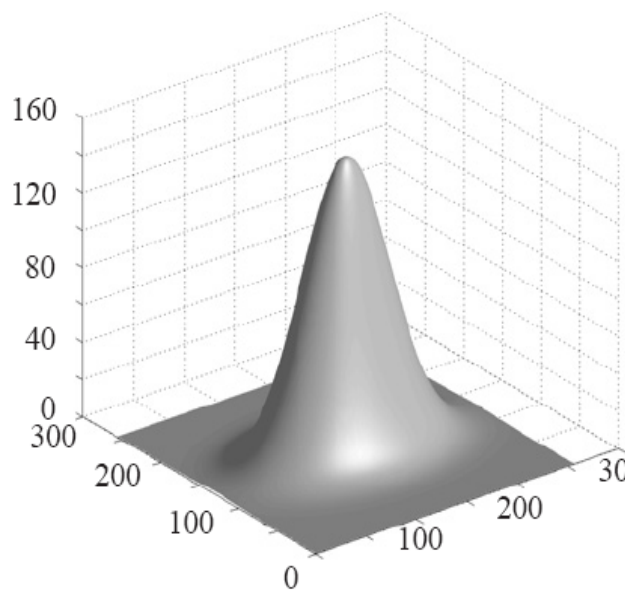
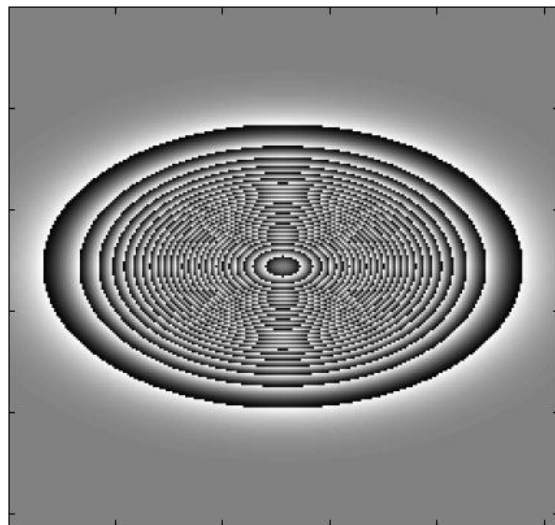
[Ishikawa, 03] (MRFs with convex priors)

[Kolmogorov & Shioura, 05,07], [Darbon, 05] (Include unary terms)

[Ahuja, Hochbaum, Orlin, 03] (convex dual network flow problem)

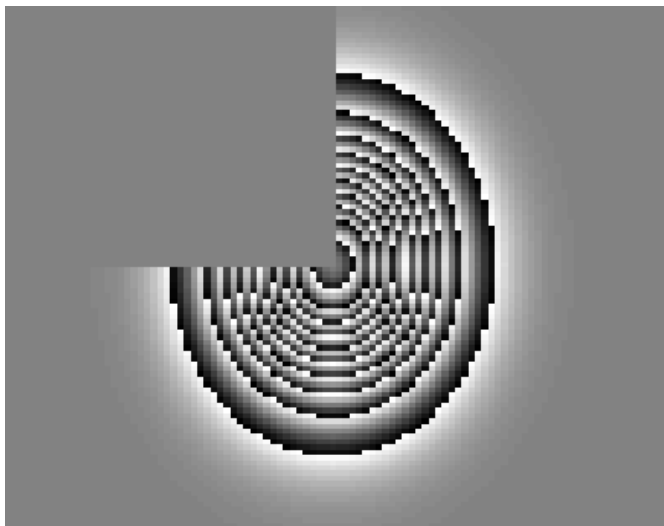
# Results

$$E_{pq}(\cdot) = (\cdot)^2$$

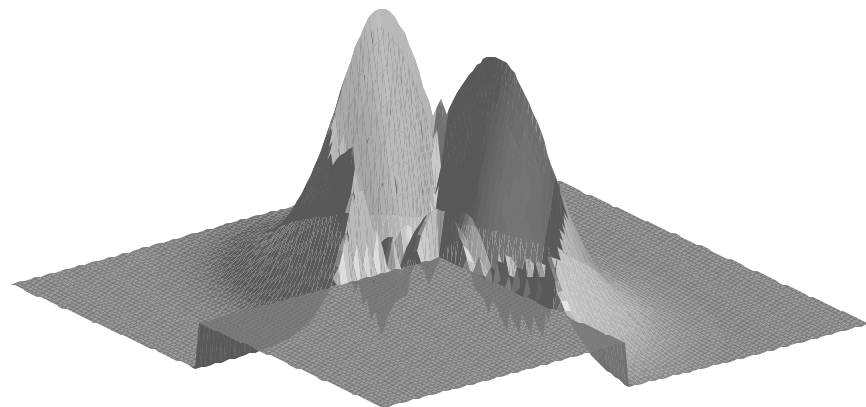


# Results

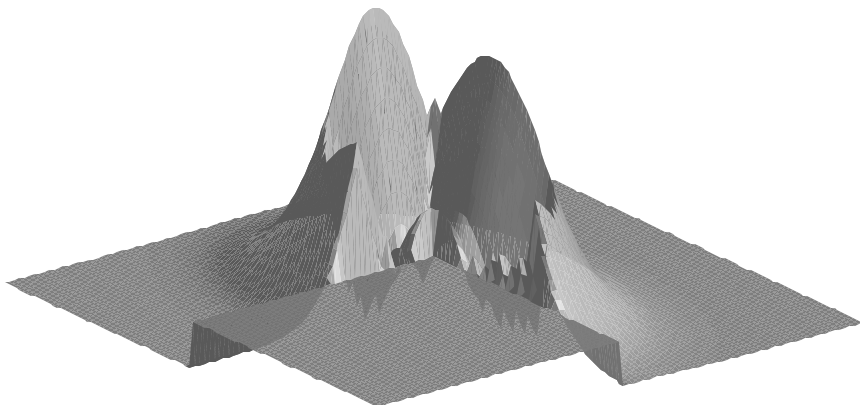
## Convex priors do not preserve discontinuities



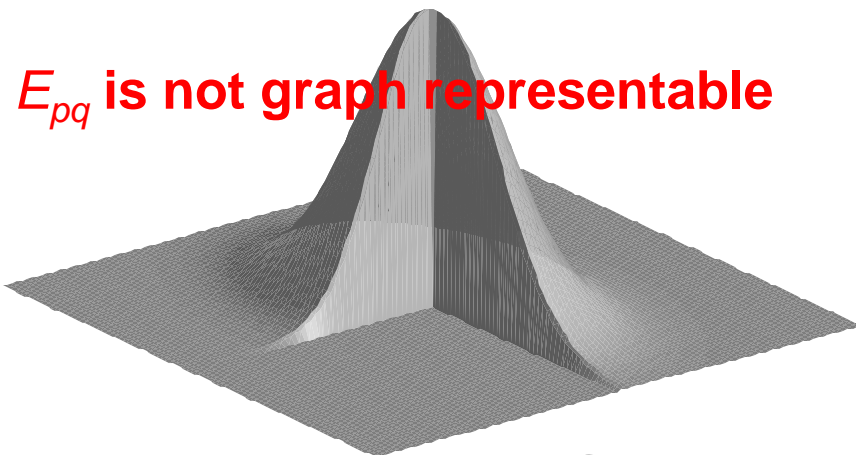
$$E_{pq}(x) = x^2$$



$$E_{pq}(x) = |x|$$



$$E_{pq}(x) = \begin{cases} x^2 & |x| \leq \pi \\ \pi^2 |x/\pi|^{0.5} & |x| > \pi \end{cases}$$



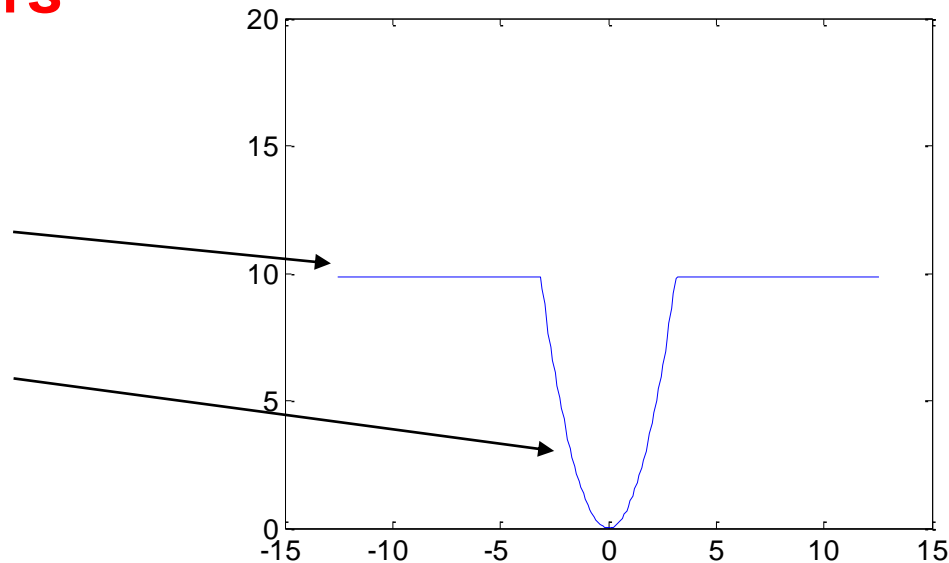
$E_{pq}$  is not graph representable

# PUMA: Non-convex priors

Ex:  $E(x) = \min(x^2, \pi^2)$

Models discontinuities

Models Gaussian noise



## Shortcomings

- ❑ Local minima are no more global minima
- ❑ Energy contains nonsubmodular terms (NP-hard)

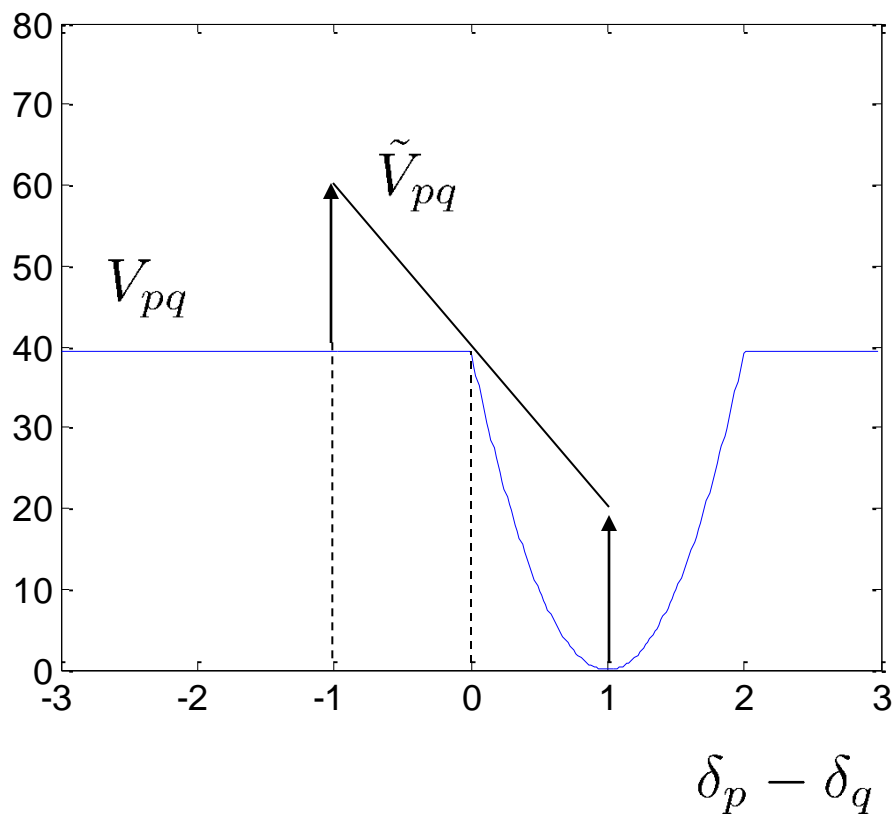
Proposed suboptimal solution: majorization minimization applied  
To PUMA binary problem

## Other suboptimal approaches

- ❑ Quadratic Pseudo Boolean Optimization (Probing [Boros et al., 2006], Improving [Rother et al., 2007])
- ❑ Sequential Tree-Reweighted Message Passing (TRW-S) [Kolmogorov, 2006]
- ❑ Dual decomposition (DD) [Komodakis et al., 2011]

# Majorizing Nonsubmodular Terms

Majorization Minimization (MM) [Lange & Fessler, 95]



$$\begin{cases} \tilde{V}(\mathbf{k}) = V(\mathbf{k}) \\ \tilde{V}(\mathbf{k} + \boldsymbol{\delta}) \geq V(\mathbf{k} + \boldsymbol{\delta}) \end{cases}$$

$$\boldsymbol{\delta}' = \arg \min_{\boldsymbol{\delta}} \tilde{V}(\mathbf{k} + \boldsymbol{\delta})$$

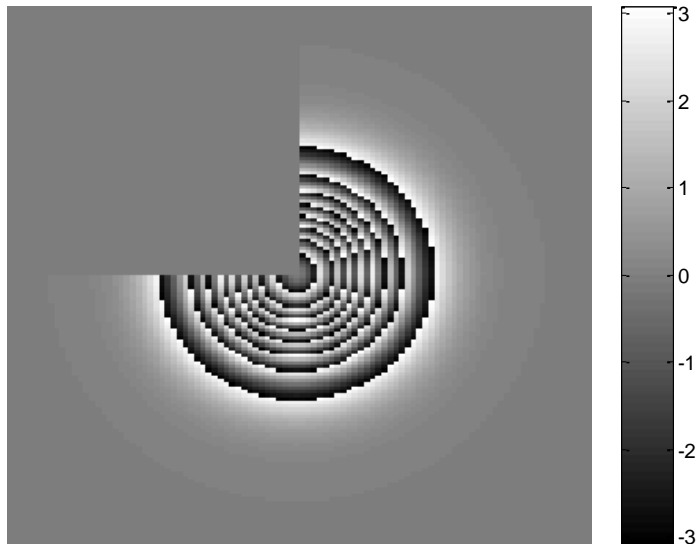
Non-increasing property

$$V(\mathbf{k} + \boldsymbol{\delta}') \leq V(\mathbf{k})$$

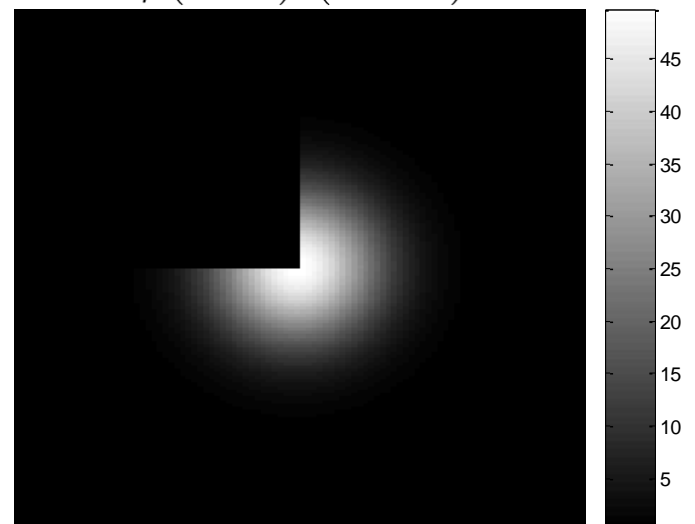
[Rother *et al.*, 05]  $\rightarrow$  similar approach for alpha expansion moves

# Results with PUMA (MM)

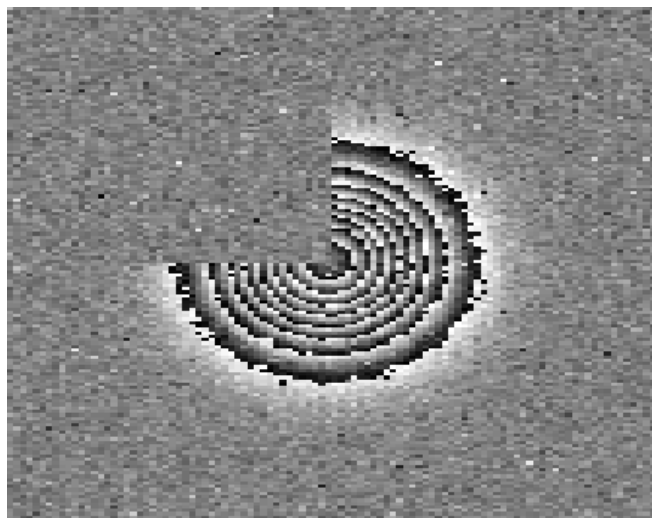
Interferogram  $\eta$



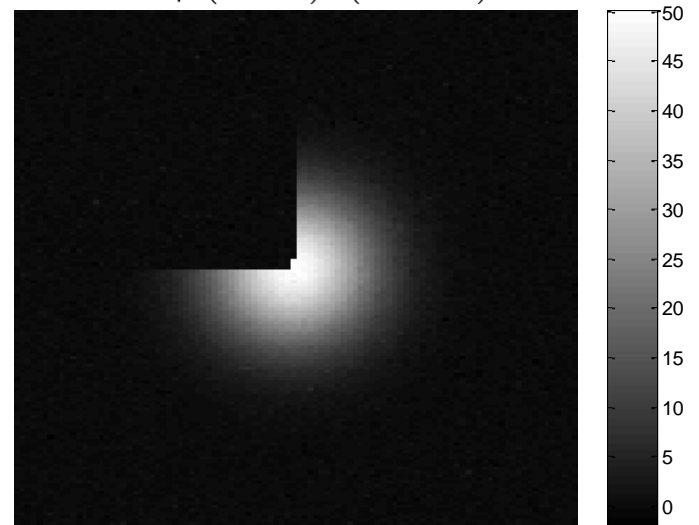
$\hat{\phi}(\text{MM})$  (8 iter)



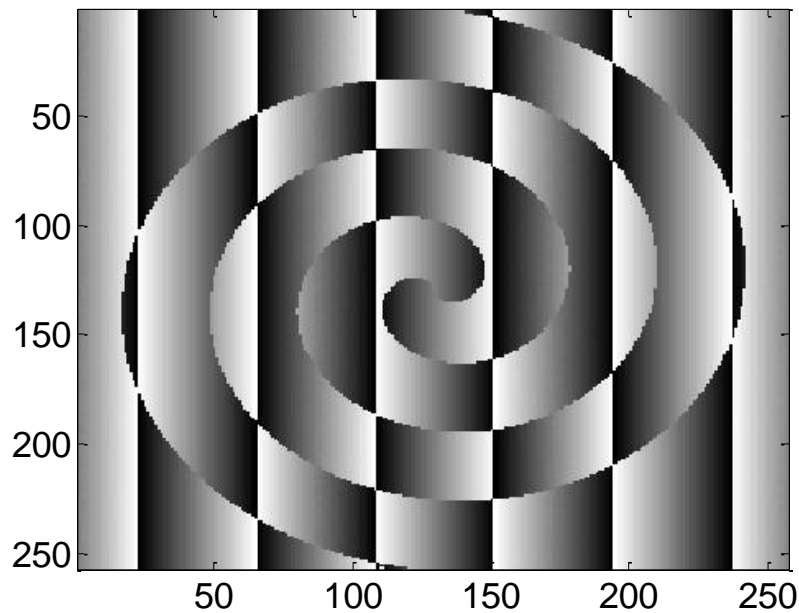
Interferogram  $\eta$



$\hat{\phi}(\text{MM})$  (8 iter)

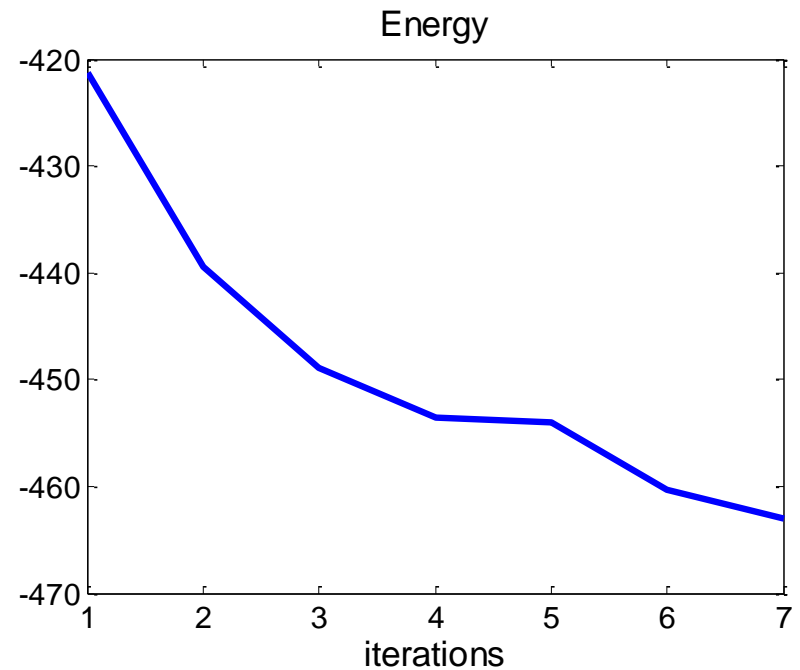
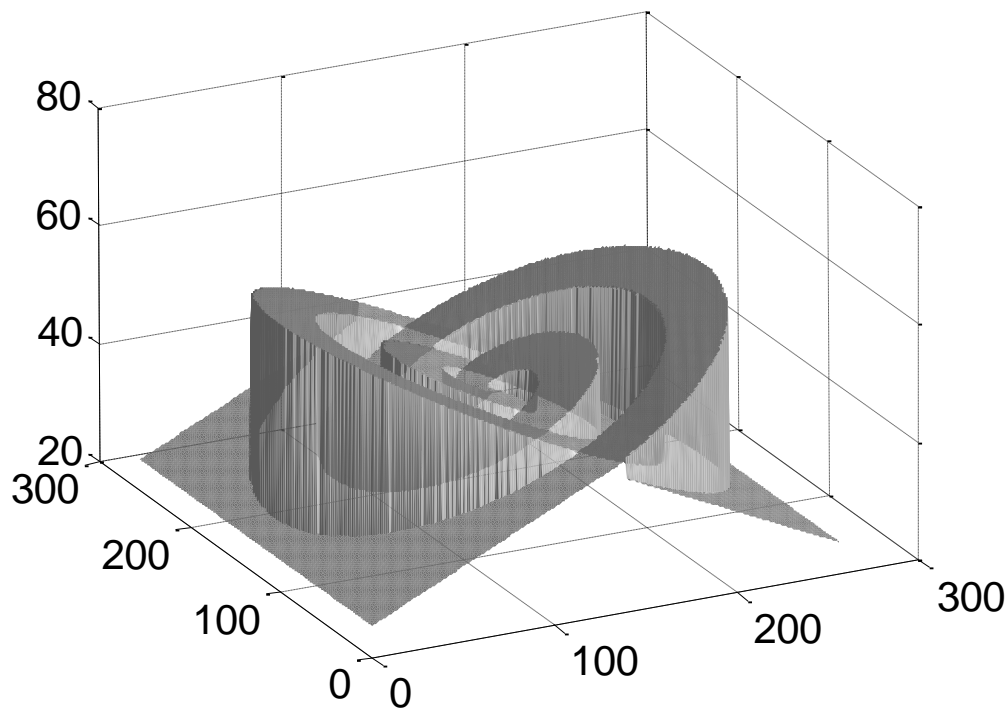






Multi-jump version of PUMA (MM)  
jumps  $d \in [1 \ 2 \ 3 \ 4]$

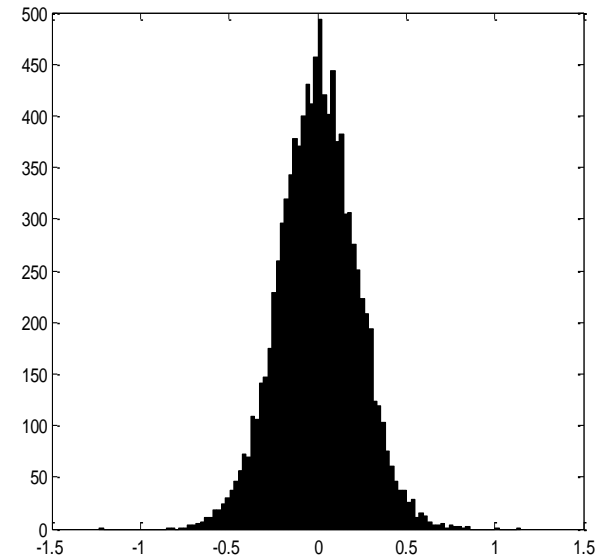
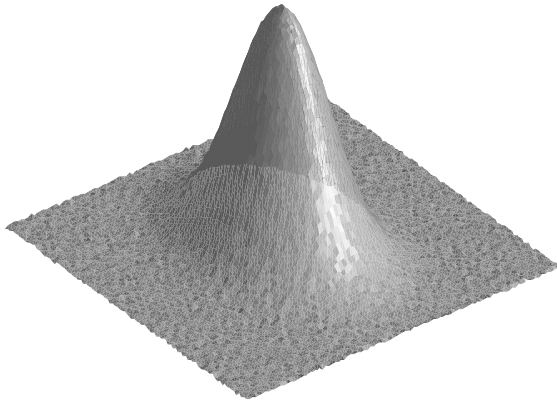
$$\delta' := \arg \min_{\delta \in \{0, d\}^{|\mathcal{V}|}} E(\phi + 2\delta\pi)$$



# Interferometric Phase Denoising

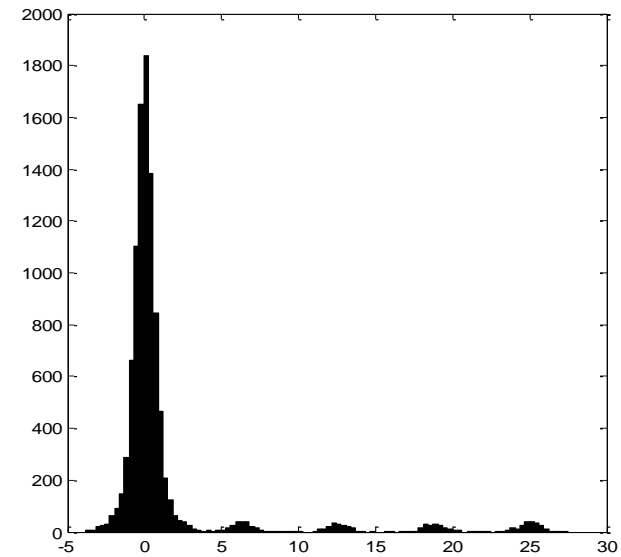
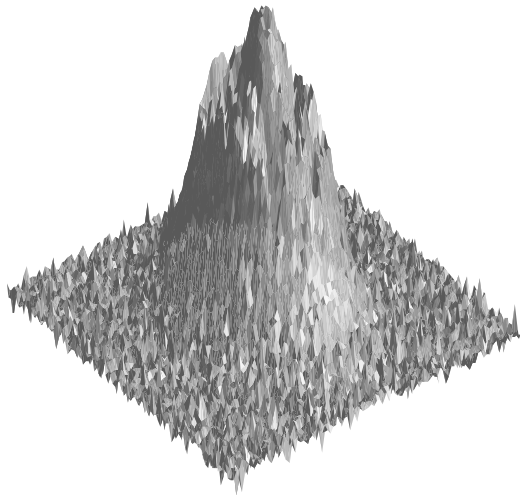
$$\sigma = 0.3$$

PU works



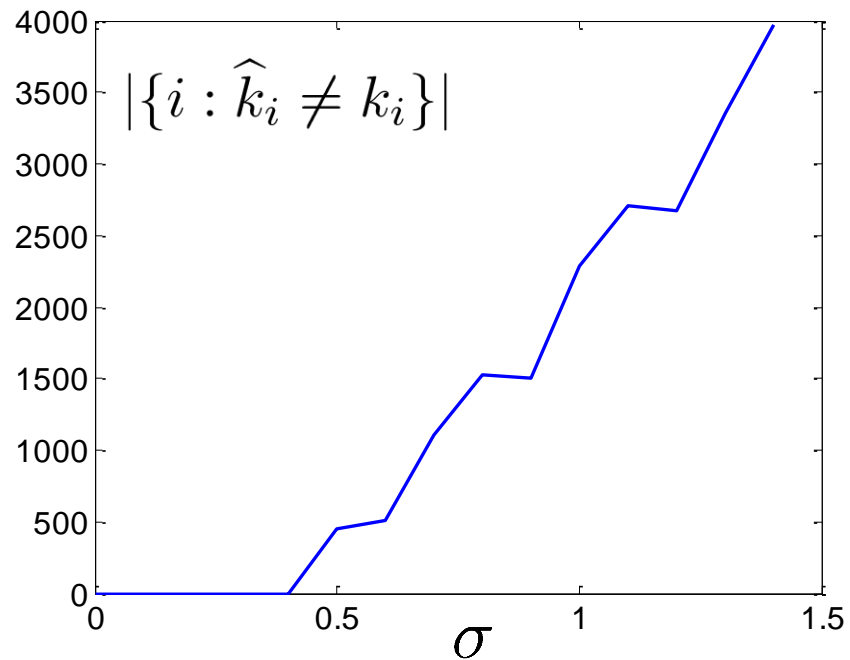
$$\sigma = 0.9$$

PU does not work

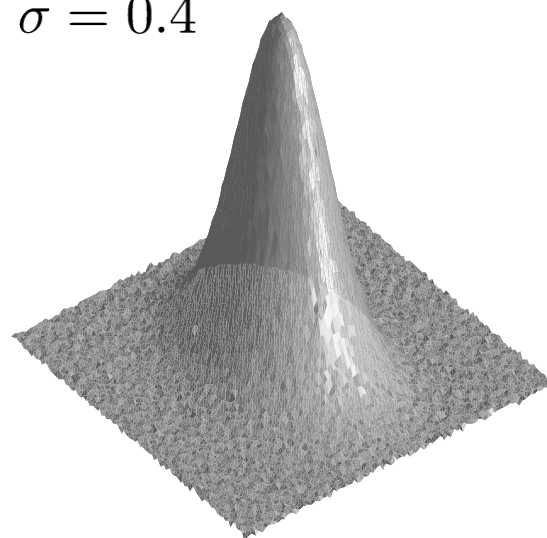


# PU Errors

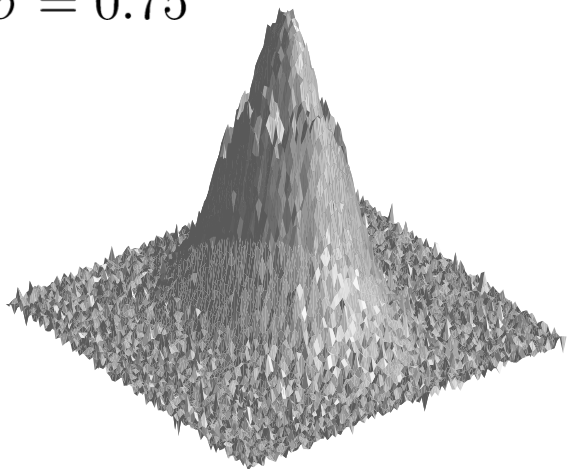
Gaussian shaped image ( $100 \times 100$ , max  $\phi = 20\pi$ )



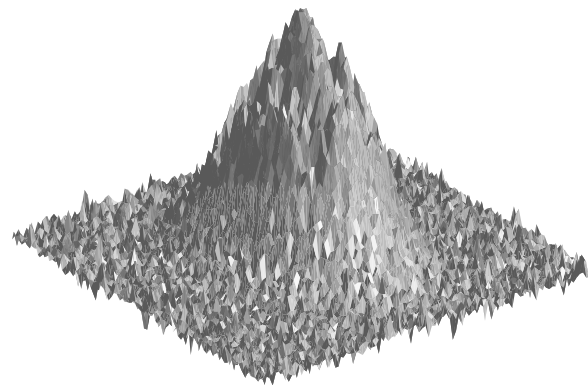
$\sigma = 0.4$



$\sigma = 0.75$

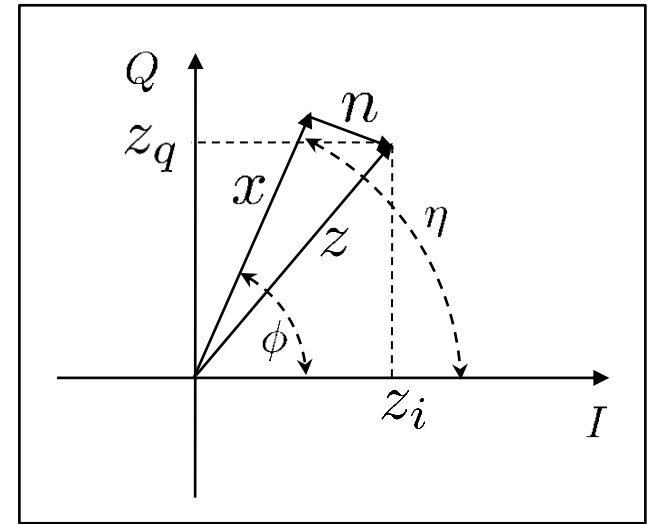


$\sigma = 1.0$

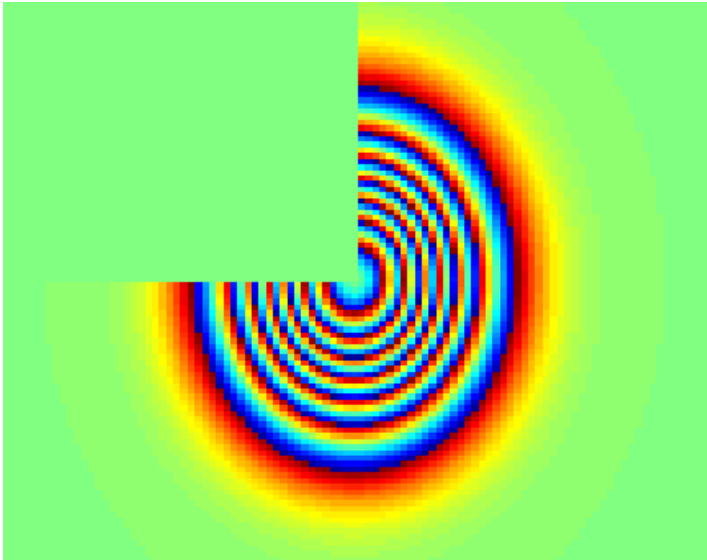


# Interferometric Phase Denoising

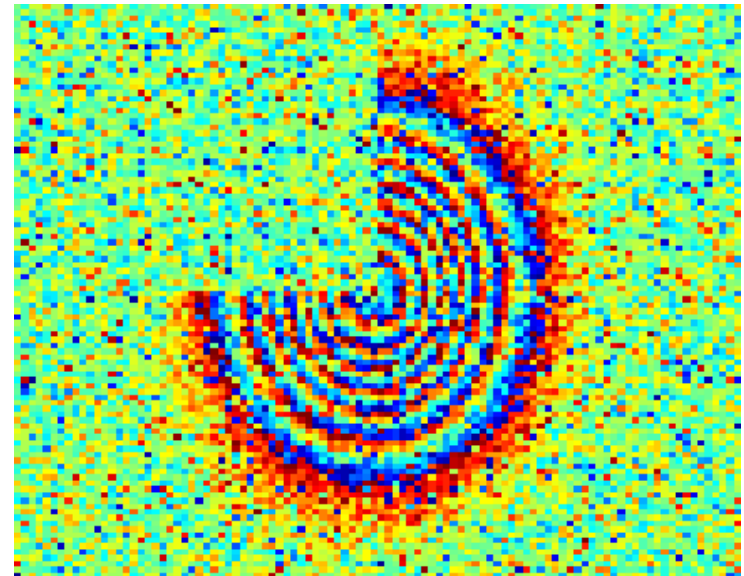
**objective:** estimate  $\mathcal{W}[\phi]$  from  $\eta$   
phase modulo  $2\pi$



original interf. image  $\phi_{2\pi} \equiv \mathcal{W}[\phi]$



observed interf. image  $\eta$



# State-of-the-art Interferometric Phase Estimation

$$z = e^{j\phi} + n$$

- parametric model for  $\phi$

PEARLS [B et al., 2008]: local first order approximation for phase and adaptive window selection (ICI [Katkovnik et al., 2006])

- denoise  $\mathbf{z}$

WFT [Kemaio, 2007]: windowed Fourier thresholding

- non-local means filtering

NL-InSAR [Deledalle, et al., 2011]: patch similarity criterion suitable to SAR images and a weighted maximum likelihood estimation interferogram with weights derived in a data-driven way

# Dictionary Based Interferometric Phase Estimation

## Motivation

- 1) sparse and redundant representations are at the heart of many state-of-the-art applications namely in image restoration
- 2) phase images exhibit a high level of self-similarity. So they admit sparse representations on suitable dictionaries.

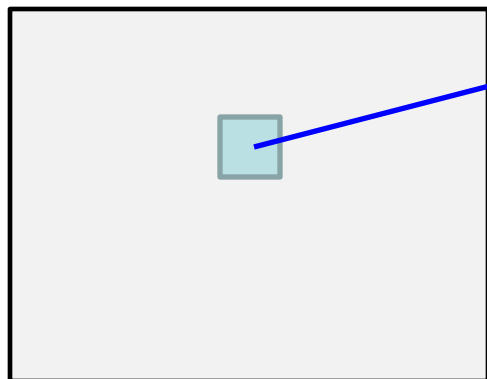
**Challenge:** the observation mechanism linking the observed phase  $\eta$  with the interferometric phase  $\phi_{2\pi}$  is nonlinear.

**Observation:** the fact that the phase image  $\phi$  is self-similar implies that  $e^{j\phi}$  is self-similar

**Our approach:** learn sparse representations for  $e^{j\phi}$  and from them infer  $\phi$

# Interferometric Phase Estimation via Sparse Regression

Complex valued image



patch of size  $\sqrt{m} \times \sqrt{m}$  at pixel  $i$

$$\mathbf{z}_i = \mathbf{x}_i + \mathbf{n}_i \in \mathbb{C}^m$$

noise vector

original vector

observed vector

$\mathbf{D} \equiv [\mathbf{d}_1, \dots, \mathbf{d}_k] \in \mathbb{C}^{m \times k}$  dictionary with respect to which  $\mathbf{x}_i$  admits a sparse representation

$$\hat{\mathbf{x}}_i = \mathbf{D} \hat{\boldsymbol{\alpha}}_i \quad \min_{\boldsymbol{\alpha}} \|\boldsymbol{\alpha}\|_0, \quad \text{s.t.:} \quad \|\mathbf{D} \boldsymbol{\alpha} - \mathbf{z}_i\|_2^2 \leq \delta$$

estimation error  $\boldsymbol{\varepsilon}_i = \hat{\mathbf{x}}_i - \mathbf{x}_i$

iid noise

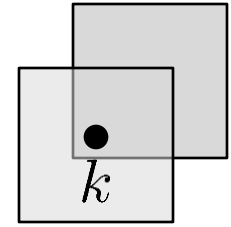
$\Rightarrow$

$$\frac{\|\boldsymbol{\varepsilon}_i\|_2^2}{\|\mathbf{n}_i\|_2^2} \simeq \frac{p}{m}$$

$$p = \|\hat{\boldsymbol{\alpha}}\|_0$$



# Interferometric Phase Estimation



$\mathcal{P}_k \rightarrow$  the set of patches containing the pixel  $k$

$\hat{x}_i = x_i + \varepsilon_i, \quad i \in \mathcal{P}_k$  the set of estimates of  $x_k$  obtained from patches  $i \in \mathcal{P}_k$

Maximum likelihood estimate of  $x_i = ae^{j\phi}$

(assume that  $\varepsilon_i = [\varepsilon_1, \dots, \varepsilon_p]$  is  $\mathcal{N}(\mathbf{0}, \mathbf{C})$  )

$$\hat{\phi}_{2\pi} = \arg \left( \sum_{j=1}^q \hat{x}_j \gamma_j \right) \quad \hat{a} = \frac{\left| \sum_{j=1}^q \hat{x}_j \gamma_j \right|}{\sum_{j=1}^q \gamma_j}$$

where  $\gamma_j := \sum_{k=1}^q [\mathbf{C}^{-1}]_{jk}$ .

in practice  $\gamma_j$  is very hard to compute and we take  $\gamma_j = c^{te}$

# Dictionary Learning

find a dictionary representing accurately the image patches with the smallest possible number of atoms.

formalization under the regularization framework

$$\min_{\mathbf{D} \in \mathcal{C}, \mathbf{A}} L(\mathbf{D}, \mathbf{A}) \quad L(\mathbf{D}, \mathbf{A}) = (1/2) \|\mathbf{Z} - \mathbf{D}\mathbf{A}\|_F^2 + \lambda \|\mathbf{A}\|_1,$$

where  $\mathcal{C} := \{\mathbf{D} \in \mathbb{C}^{m \times k} : |\mathbf{d}_j^H \mathbf{d}_j| \leq 1, j = 1, \dots, k\}$

and  $\mathbf{Z} = [\mathbf{z}_1, \dots, \mathbf{z}_{N_p}]$  and  $\mathbf{A} = [\boldsymbol{\alpha}_1, \dots, \boldsymbol{\alpha}_{N_p}]$

**DL Algorithm:** alternating proximal minimization (APM)

$$\begin{cases} \mathbf{D}^{k+1} \in \arg \min_{\mathbf{D} \in \mathcal{C}} L(\mathbf{D}, \mathbf{A}^k) + \lambda \|\mathbf{D} - \mathbf{D}^k\|_F^2 \\ \mathbf{A}^{k+1} \in \arg \min_{\mathbf{A}} L(\mathbf{D}^{k+1}, \mathbf{A}) + \lambda \|\mathbf{A} - \mathbf{A}^k\|_F^2 \end{cases}$$

Convergence (based on the Kurdyka-Lojasiewicz inequality)  
[Attouch et al. 10], [Xu, Yin, 2012]

# Dictionary Learning

**drawback:** alternating proximal minimization takes too long (order of  $10^4$  sec) in a typical image scenario ( $N_p = 100000$ ,  $m = 100$ , and  $k = 200$ )

**another DL algorithm:** Direct Optimization (DM) method  
(non-convex proximal splitting results) [Rakotomamonjy, 2012]

$$\begin{cases} \mathbf{D}^{k+1} = \text{prox}_{\eta_k \iota_{\mathcal{D}}}(\mathbf{D}^k - \eta_k(\mathbf{Z} - \mathbf{D}^k \mathbf{A}^k)(\mathbf{A})^H) \\ \mathbf{A}^{k+1} = \text{prox}_{\eta_k \Omega_A}(\mathbf{D}^k - \eta_k(\mathbf{D}^k)^H(\mathbf{Z} - \mathbf{D}^k \mathbf{A}^k)) \end{cases}$$

projection on the unit sphere

soft threshold

**drawback:** direct optimization yields local minima poorer than APM

**another DL algorithm:** Online Dictionary Learning (ODL): [Mairal et al. 2010]

# Dictionary Learning

Online Dictionary Learning (ODL): [Mairal et al. 2010]

Select randomly  $\mathbf{z}^t \equiv [\mathbf{z}_i^t \ i = 1, \dots, \eta]$  from  $\mathbf{z}$

(Sparse coding: BPDN)

$$\boldsymbol{\alpha}^t := \arg \min_{\boldsymbol{\alpha} \in \mathbb{C}^{k \times \eta}} (1/2) \|\mathbf{z}^t - \mathbf{D}\boldsymbol{\alpha}\|_F^2 + \lambda \|\boldsymbol{\alpha}\|_1$$

$$\min_{\mathbf{D} \in \mathcal{C}} \frac{1}{S_t} \sum_{i=1}^t w_i \left\{ (1/2) \|\mathbf{z}^i - \mathbf{D}\boldsymbol{\alpha}^i\|_F^2 + \lambda \|\boldsymbol{\alpha}^i\|_1 \right\}$$

$\mathbf{D}^t$  converges to the stationary points of

$$(1/2) \|\mathbf{Z} - \mathbf{D}\mathbf{A}\|_F^2 + \lambda \|\mathbf{A}\|_1, \\ \mathbf{D} \in \mathcal{C}$$

fast sparse coding via ADMM [B & Figueiredo, 2010]

$$\boldsymbol{\alpha}^t := \mathbf{D}^H \mathbf{z}^t$$

$$\mathbf{u}^t := \boldsymbol{\alpha}^t, \mathbf{v}^t := \mathbf{0}$$

$$\mathbf{F} = (\mathbf{D}^H \mathbf{D} + \mu \mathbf{I})^{-1}$$

**while** *not converge* **do**

$$\mathbf{u}^t := \text{soft}(\boldsymbol{\alpha}^t - \mathbf{v}^t, \lambda/\mu)$$

$$\boldsymbol{\alpha}^t := \mathbf{F}(\mathbf{D}^H \mathbf{z}^t + \mu(\mathbf{u}^t + \mathbf{v}^t))$$

$$\mathbf{v}^t := \mathbf{v}^t - (\boldsymbol{\alpha}^t - \mathbf{u}^t)$$

**end**

computational complexity:  $O(km^2 + \eta km)$

# The Proposed Algorithm

## SplnPHASE [Hongxing, B, Katkovnik, 2013]

---

**Input:**  $\mathbf{z} \in \mathbb{C}^{N_1 \times N_2}$  (complex valued image)

**Output:**  $\hat{\phi} \in \mathbb{R}^{N_1 \times N_2}$  (absolute phase estimate)

**Begin**

$\mathbf{z}_i \leftarrow \mathbf{M}_i \mathbf{z}, i = \dots, N_p$  (extract patches)

$\mathbf{D} \leftarrow \text{DL}(\mathbf{z}_i, i = 1, \dots, N_p)$  (learn the dictionary)

$\alpha_i \leftarrow \text{OMP}(\mathbf{D}, \mathbf{z}_i, i = 1, \dots, N_p)$  (sparse coding)

$\mathbf{x}_i \leftarrow \mathbf{D} \alpha_i, i = 1, \dots, N_p$  (path estimate)

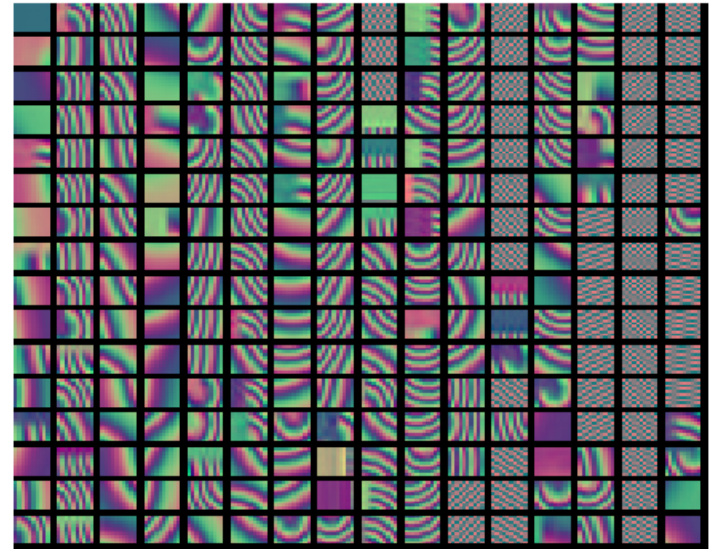
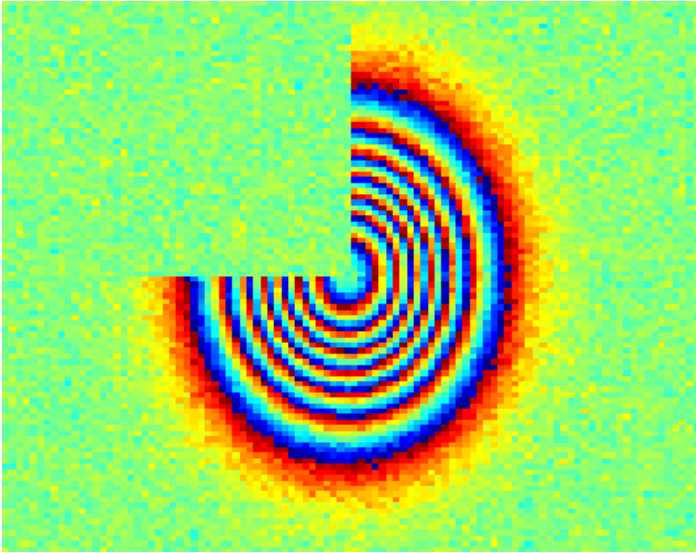
$\mathbf{x} \leftarrow \text{compose}(\mathbf{x}_i, i = 1, \dots, N_p)$  (path compose)

$\hat{\phi}_{2\pi} \leftarrow \arg(\mathbf{x})$  (interferometric phase estimate)

$\hat{\phi} \leftarrow \text{PUMA}(\hat{\phi}_{2\pi})$  (phase unwrapping)

**End**

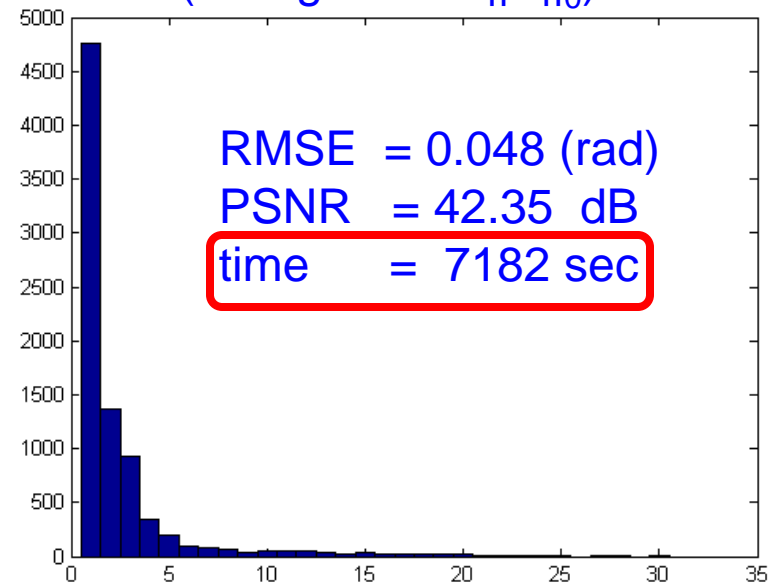
# DL (APM): Example (truncated Gaussian - $\sigma = 0.3$ ) $\sqrt{m} = 12, k = 256$ (learned dictionary – APM)



$$\text{RMSE} := \frac{\|\mathcal{W}(\hat{\phi}_{2\pi} - \phi_{2\pi})\|_F}{\sqrt{N}}$$

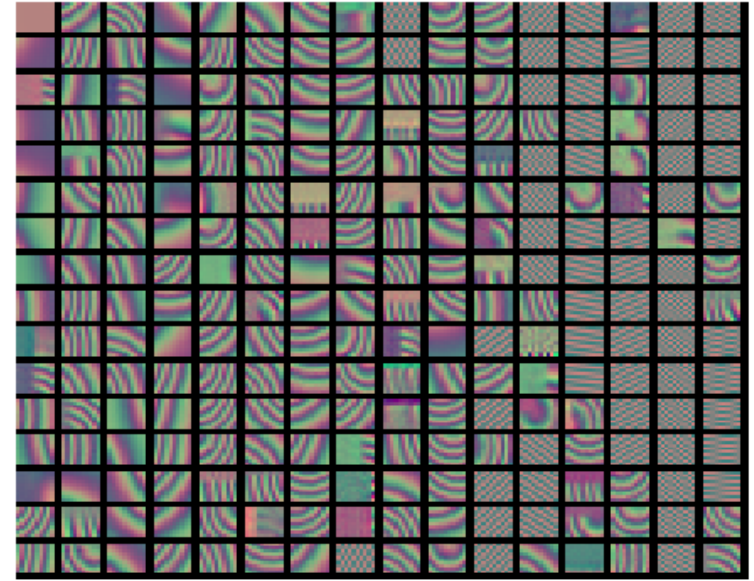
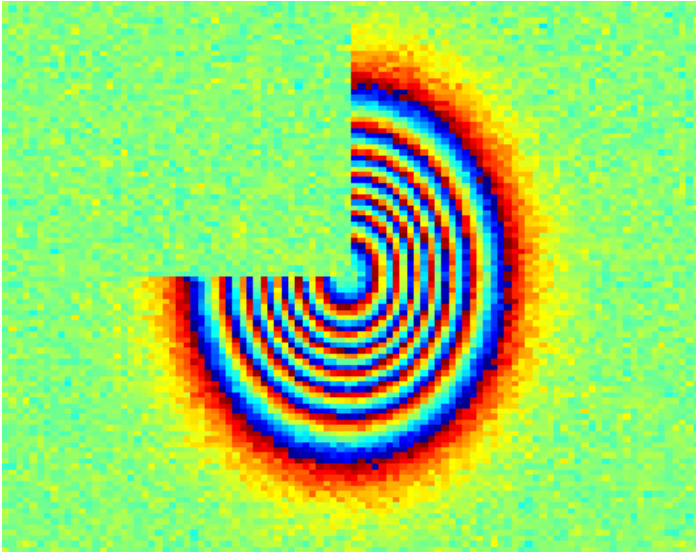
$$\text{PSNR} := \frac{4N\pi^2}{\|\mathcal{W}(\hat{\phi}_{2\pi} - \phi_{2\pi})\|_F^2}$$

(histogram of  $\|\alpha\|_0$ )



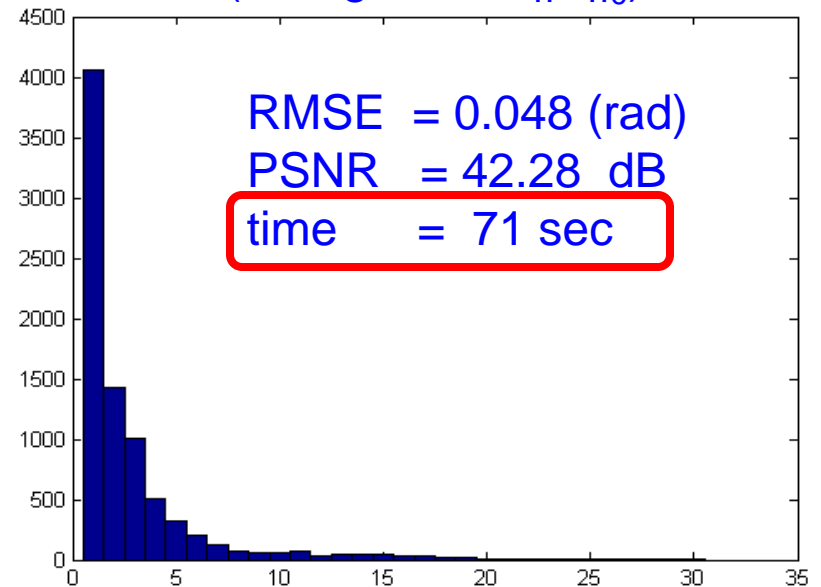
$$\frac{\|\mathcal{W}(\eta - \phi_{2\pi})\|_F^2}{\|\mathcal{W}(\hat{\phi}_{2\pi} - \phi_{2\pi})\|_F^2} = 20 \simeq \frac{1}{2} \frac{m}{\bar{p}}$$

**DL (ODL): Example** (truncated Gaussian -  $\sigma = 0.3$ )  $\sqrt{m} = 12$ ,  $k = 256$   
(learned dictionary – ODL)



(histogram of  $\|\alpha\|_0$ )

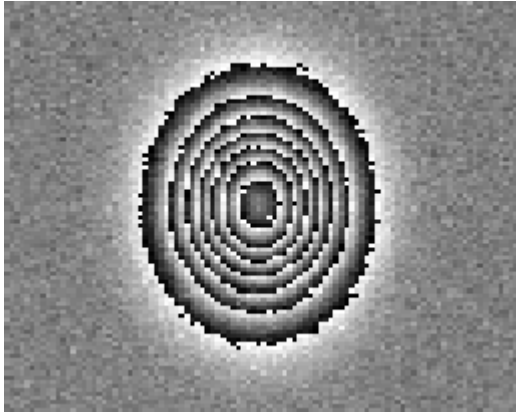
$$\frac{\|\mathcal{W}(\boldsymbol{\eta} - \boldsymbol{\phi}_{2\pi})\|_F^2}{\|\mathcal{W}(\hat{\boldsymbol{\phi}}_{2\pi} - \boldsymbol{\phi}_{2\pi})\|_F^2} = 20 \simeq \frac{1}{2} \frac{m}{\bar{p}}$$



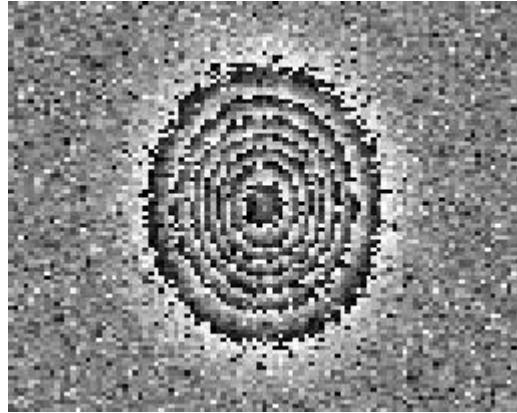


# Restored Images

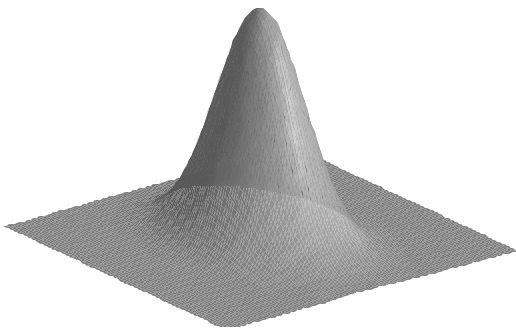
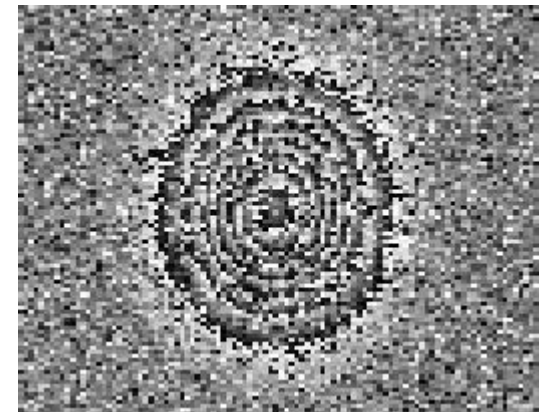
$\sigma = 0.5$



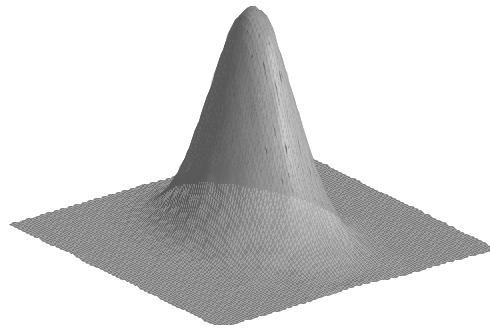
$\sigma = 1.0$



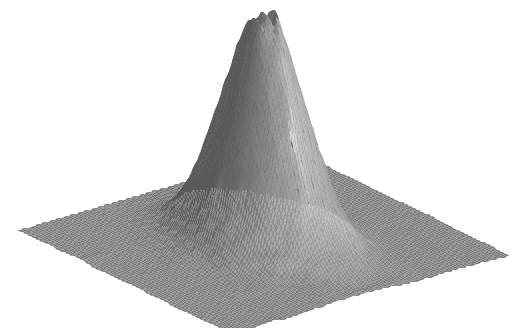
$\sigma = 1.5$



RMSE = 0.052

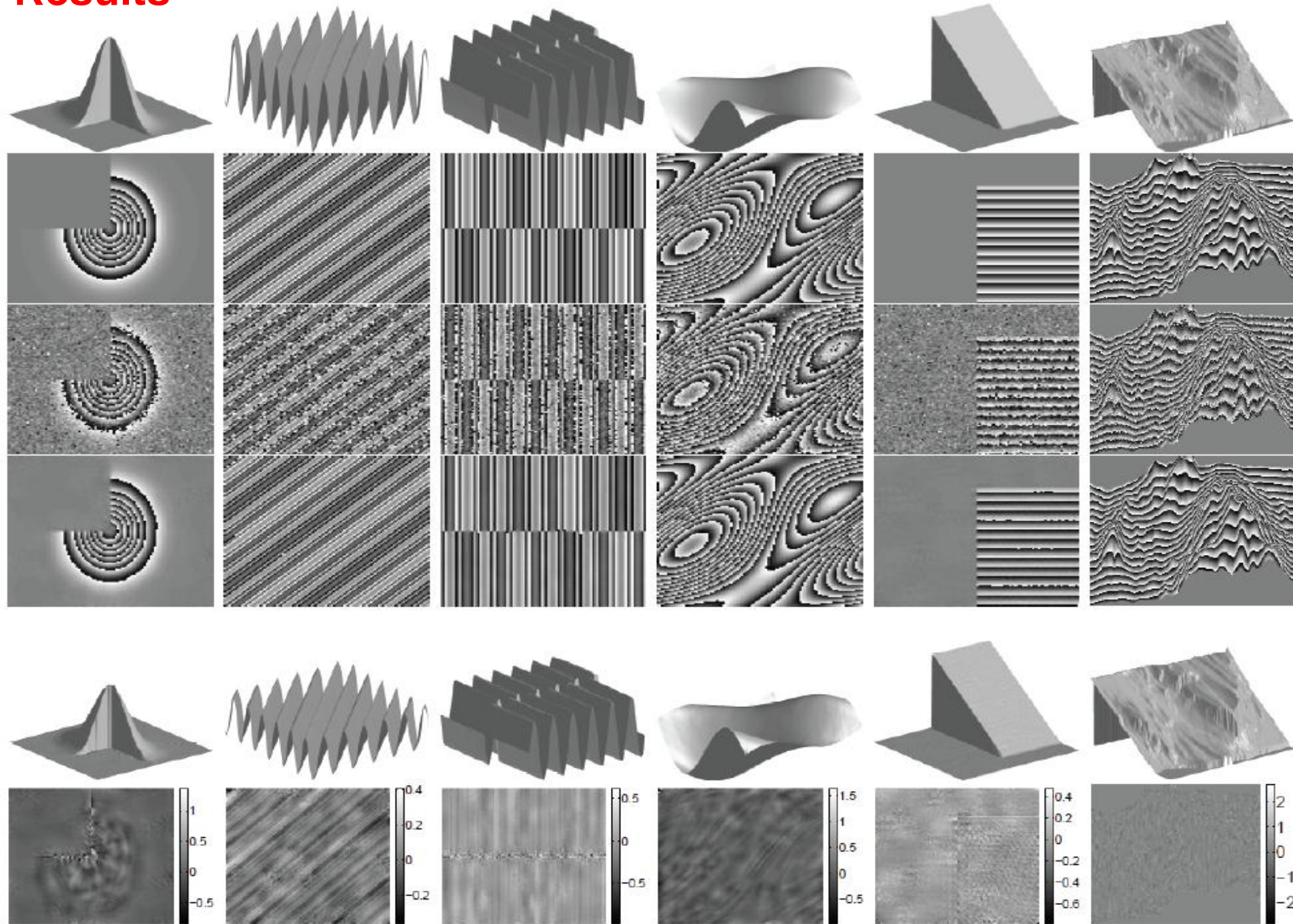


RMSE = 0.108



RMSE = 0.174

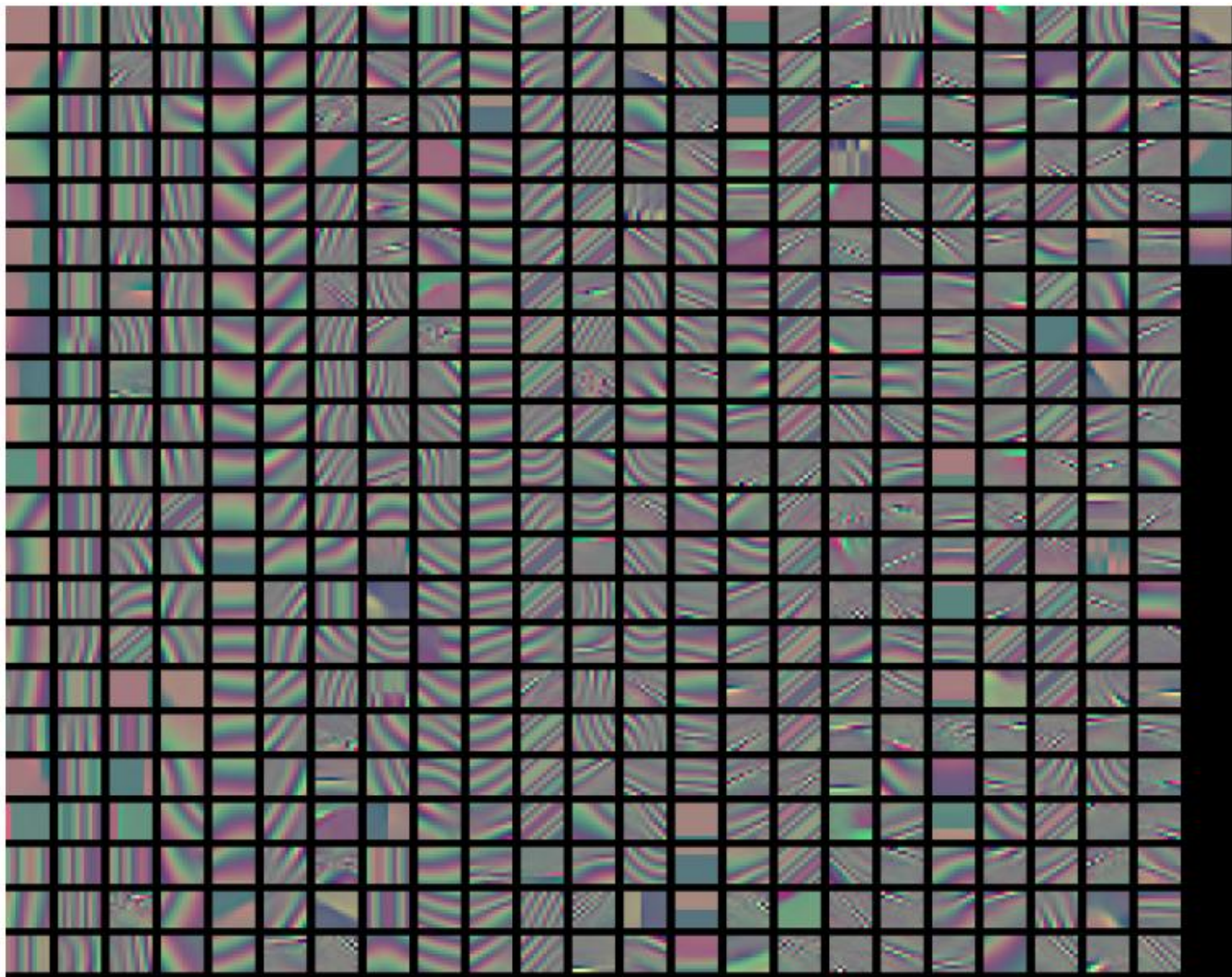
# Results





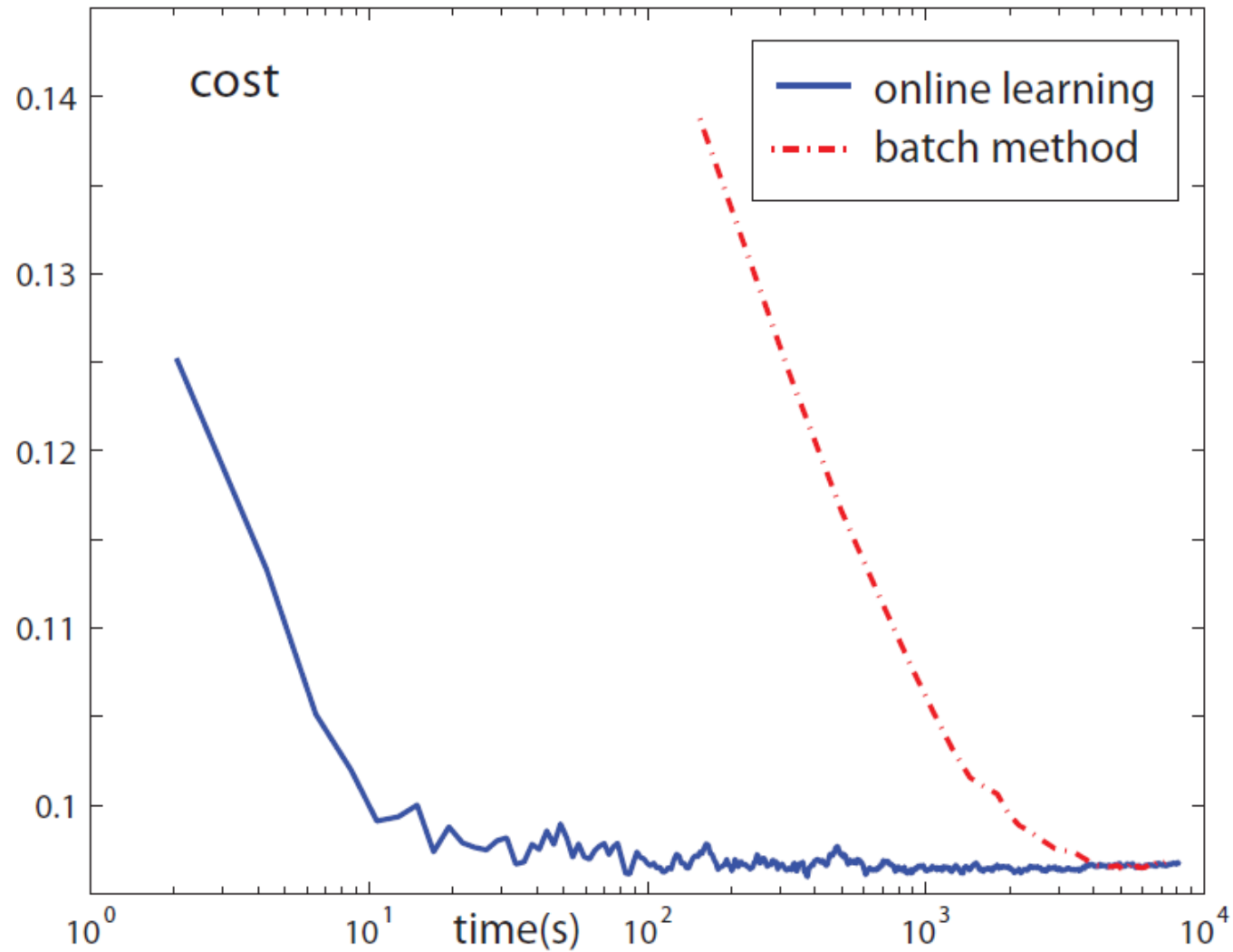
## Dictionary Learned from 6 Images (shown before)

$$\sqrt{m} = 12, k = 512$$



## DL: Online (ODL) Versus Batch (APM)

$$\sqrt{m} = 12, k = 512$$



# Comparisons with Competitors

Surf.	$\sigma$	PSNR (dB)			PSNR <sub>a</sub> (dB)			NELP			TIME (s)		
		Sp(ld)	Sp(pd)	W	Sp(ld)	Sp(pd)	W	Sp(ld)	Sp(pd)	W	Sp(ld)	Sp(pd)	W
Trunc. Gauss.	0.3	42.51	<b>42.88</b>	40.29	42.51	<b>42.88</b>	40.29	<b>0</b>	<b>0</b>	<b>0</b>	69	<b>6</b>	10
	0.5	39.63	<b>39.95</b>	36.71	39.63	<b>39.95</b>	36.71	<b>0</b>	<b>0</b>	<b>0</b>	74	<b>4</b>	10
	0.7	35.69	<b>36.96</b>	34.26	35.85	<b>36.98</b>	34.37	8	<b>3</b>	10	72	<b>3</b>	10
	0.9	33.52	<b>36.04</b>	32.79	33.52	<b>36.23</b>	32.79	<b>0</b>	7	<b>0</b>	72	<b>3</b>	10
Sinu.	0.3	<b>48.94</b>	47.77	35.76	<b>48.94</b>	47.77	35.76	<b>0</b>	<b>0</b>	0	61	<b>2</b>	10
	0.5	41.91	<b>43.50</b>	31.48	41.91	<b>43.50</b>	31.48	<b>0</b>	<b>0</b>	<b>0</b>	65	<b>2</b>	10
	0.7	38.44	<b>41.20</b>	28.90	38.44	<b>41.20</b>	28.90	<b>0</b>	<b>0</b>	<b>0</b>	65	<b>2</b>	10
	0.9	36.42	<b>39.30</b>	26.36	36.42	<b>39.30</b>	26.36	<b>0</b>	<b>0</b>	<b>0</b>	63	<b>2</b>	10
Sinu. discon.	0.3	<b>44.45</b>	42.29	35.91	<b>44.45</b>	42.29	35.91	<b>0</b>	<b>0</b>	<b>0</b>	63	<b>6</b>	10
	0.5	<b>39.41</b>	38.61	31.86	<b>39.41</b>	38.61	31.86	<b>0</b>	<b>0</b>	<b>0</b>	72	<b>3</b>	10
	0.7	<b>37.09</b>	35.95	29.86	<b>37.09</b>	35.95	29.95	<b>0</b>	<b>0</b>	1	71	<b>2</b>	10
	0.9	<b>34.17</b>	34.00	27.64	<b>34.17</b>	34.00	27.71	<b>0</b>	<b>0</b>	6	66	<b>2</b>	10
Mount.	0.3	<b>40.66</b>	38.90	40.00	<b>40.66</b>	38.90	40.00	<b>0</b>	<b>0</b>	<b>0</b>	57	<b>10</b>	<b>10</b>
	0.5	<b>37.20</b>	35.66	36.55	<b>37.20</b>	35.66	36.55	<b>0</b>	<b>0</b>	<b>0</b>	60	<b>6</b>	10
	0.7	<b>34.35</b>	33.29	34.17	<b>34.35</b>	33.29	34.17	<b>0</b>	<b>0</b>	<b>0</b>	62	<b>5</b>	10
	0.9	<b>32.55</b>	31.66	32.31	<b>32.70</b>	31.79	32.31	1	1	<b>0</b>	60	<b>4</b>	10
Shear plane	0.3	<b>49.36</b>	47.01	40.67	<b>49.36</b>	47.01	40.67	0	<b>0</b>	<b>0</b>	57	23	<b>10</b>
	0.5	<b>42.95</b>	44.05	37.07	<b>42.95</b>	44.05	37.07	<b>0</b>	<b>0</b>	<b>0</b>	63	<b>2</b>	10
	0.7	38.39	<b>39.58</b>	34.13	38.39	<b>39.58</b>	34.13	<b>0</b>	<b>0</b>	<b>0</b>	68	<b>2</b>	10
	0.9	33.53	<b>38.72</b>	33.24	33.53	<b>38.72</b>	33.24	<b>0</b>	<b>0</b>	<b>0</b>	72	<b>2</b>	10
Long's Peak	0.3	35.49	<b>35.68</b>	35.40	35.51	<b>35.69</b>	35.41	<b>28</b>	<b>28</b>	<b>28</b>	515	179	<b>31</b>
	0.5	33.05	<b>33.19</b>	32.89	33.08	<b>33.24</b>	32.93	32	33	<b>31</b>	357	77	<b>30</b>
	0.7	31.32	<b>31.46</b>	31.19	31.46	<b>31.53</b>	31.28	<b>26</b>	48	32	326	42	<b>30</b>
	0.9	29.97	<b>30.17</b>	29.90	30.09	<b>30.26</b>	29.99	34	<b>32</b>	35	308	<b>27</b>	30

# Non-Gaussian and Non-additive Noise

quite often, we are just given interferferograms  $\eta = \mathcal{W}(\phi + \varepsilon)$

$$\Rightarrow e^{j\eta} = e^{j(\phi + \varepsilon)}$$

if  $|\varepsilon| \ll \pi \Rightarrow e^{j\eta} \simeq e^{j\phi} + \boxed{je^{j\phi}\varepsilon} \rightarrow$  additive noise

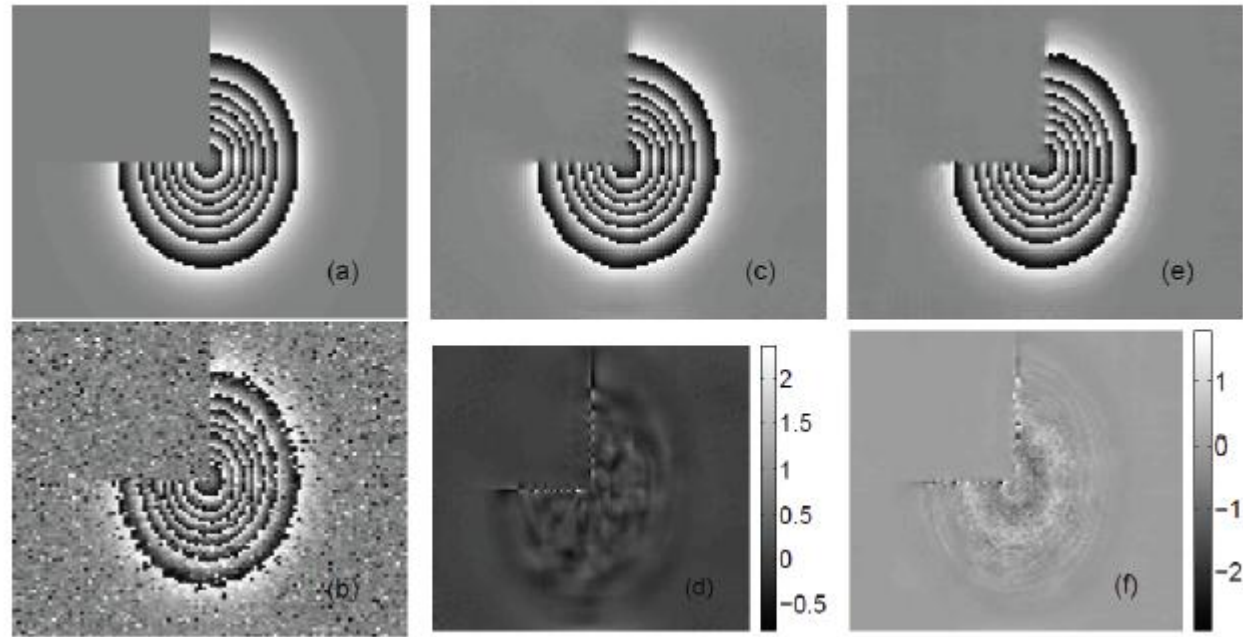
Define  $\mathbf{z} = \frac{e^{j\eta}}{\sigma_\varepsilon}$

Example: Interferometric SAR (InSAR)

$$\sigma_\varepsilon^2(\gamma) = \frac{\pi^3}{3} - \pi \arcsin(\gamma) + \arcsin^2(\gamma) + \frac{\text{Li}_2(\gamma)}{2}$$

 Interferometric coherence

# Application to InSAR



Indicator	Algorithm	coherence			
		0.95	0.9	0.85	0.8
PSNR (dB)	NL-InSAR	31.70	31.69	31.68	28.97
	SpInPHASE	<b>38.00</b>	<b>35.57</b>	<b>33.48</b>	<b>31.74</b>
PSNR <sub>a</sub> (dB)	NL-InSAR	32.09	32.49	32.82	31.52
	SpInPHASE	<b>38.00</b>	<b>36.05</b>	<b>33.67</b>	<b>32.99</b>
NELP	NL-InSAR	23	45	24	202
	SpInPHASE	<b>0</b>	<b>24</b>	<b>12</b>	<b>95</b>
TIME (s)	NL-InSAR	<b>34.07</b>	<b>33.43</b>	<b>32.60</b>	<b>32.07</b>
	SpInPHASE	368.63	362.56	380.97	365.11



# Concluding Remarks

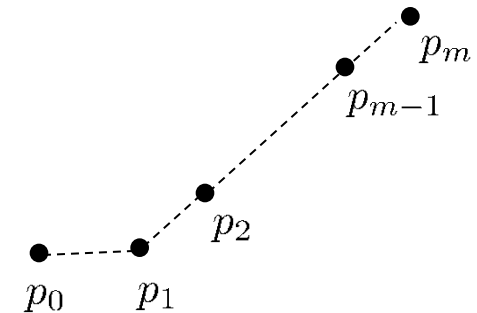
- ❑ New interferometric phase estimation via sparse coding in the complex domain
- ❑ Exploits the self similarity of the complex valued images  $e^{j\phi}$
- ❑ SpInPHASE in short
  - Online dictionary learning
  - ADMM to solve the ODL BPDN step
  - Sparse coding via OMP
  - PUMA to solve the phase unwrapping step
- ❑ State-of-the-art results, namely regarding the preservation of discontinuities coded in the interferometric phase
- ❑ Future research directions
  - Multisource phase estimation
  - Analysis dictionaries

# Phase Unwrapping Path Following Methods

Assume that  $|\phi_p - \phi_q| < \pi$   $\phi_p = \eta_p + 2k_p\pi$   $\phi_q = \eta_q + 2k_q\pi$

Then  $\phi_p - \phi_q = \mathcal{W}(\phi_p - \phi_q) = \mathcal{W}(\eta_p - \eta_q)$

PU  $\Rightarrow$  summing  $\mathcal{W}(\eta_p - \eta_q)$  over walks



$$\phi_{p_m} = \phi_{p_0} + \sum_{i=1}^m \mathcal{W}(\eta_{p_i} - \eta_{p_{i-1}})$$

Why isn't PU a trivial problem?

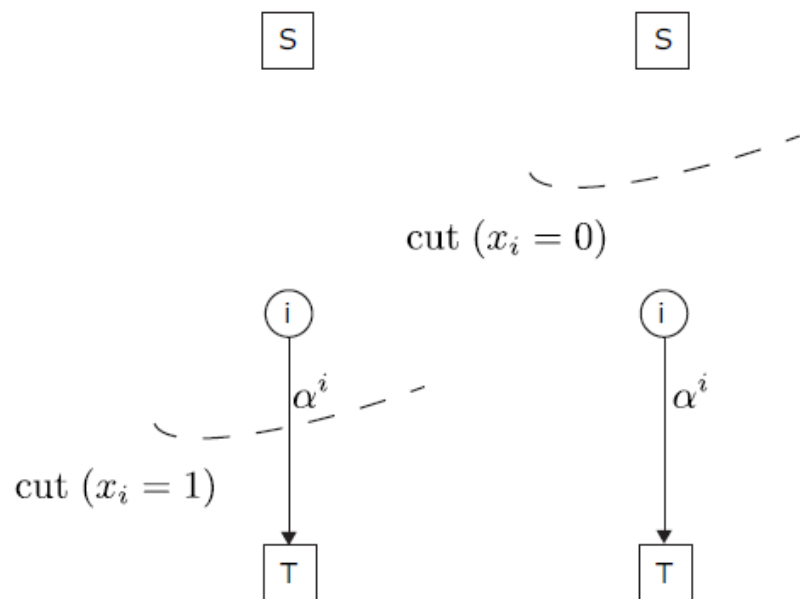
Discontinuities  
High phase rate  
Noise



$$|\phi_p - \phi_q| \geq \pi$$

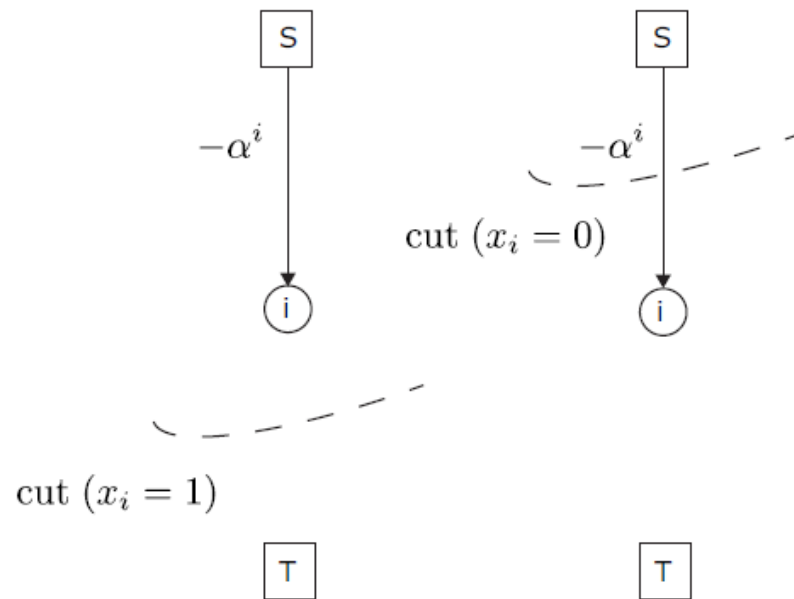
# Unary terms: $\alpha^i x_i$

$\alpha^i > 0$



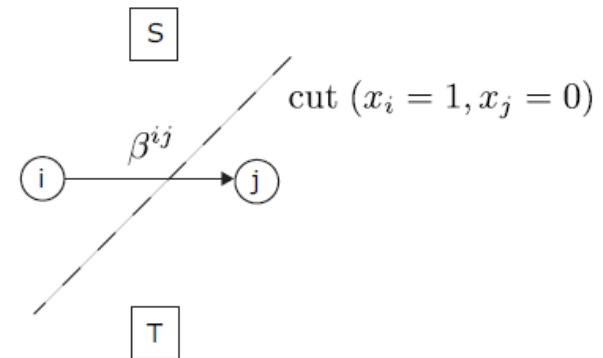
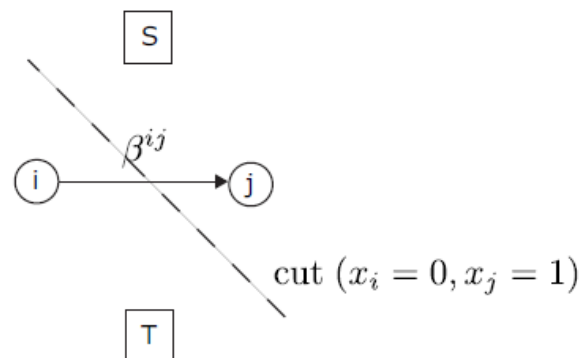
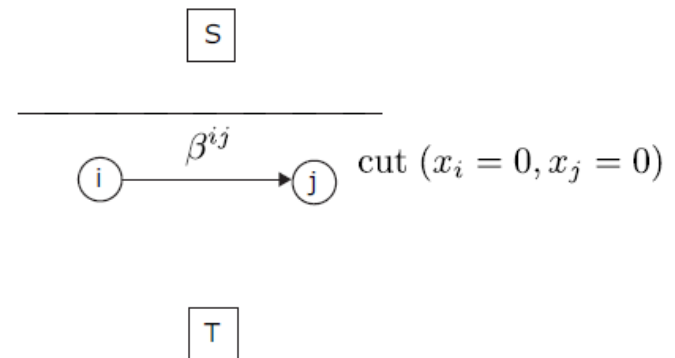
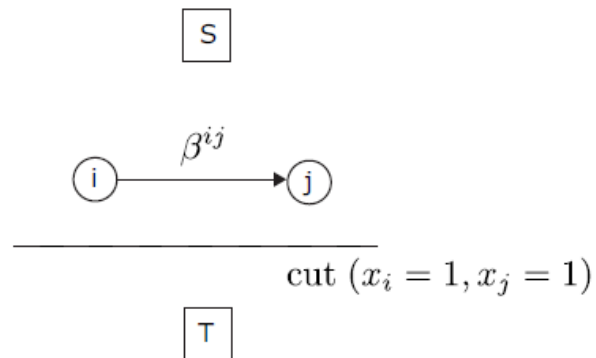
$$\text{cut}(x^i) = \alpha^i x_i$$

$\alpha^i < 0$



$$\text{cut}(x^i) = \alpha^i x_i - \alpha^i$$

Pairwise terms:  $\beta^{ij}(x_i - x_j)x_i$ ,  $\beta^{ij} \geq 0$



$$\text{cut}(x_i, x_j) = \beta^{ij}(x_i - x_j)x_i$$